

Computational Complexity of real functions

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- 1 Complexity of real functions
 - Introduction
 - Computable Analysis
 - GPAC
 - Analog Church Thesis
- 2 Toward a Complexity Theory for the GPAC
 - What is the problem ?
 - A complexity class
- 3 Conclusion

Motivating example

Motivating example

Example (Sine function)

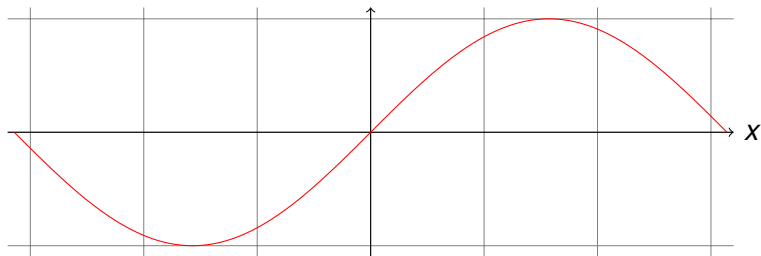
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⇒ “clearly \sin is computable:”

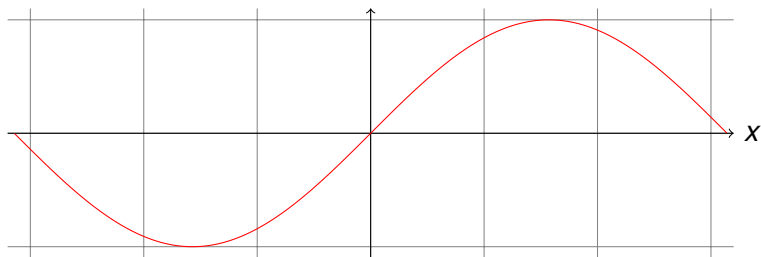


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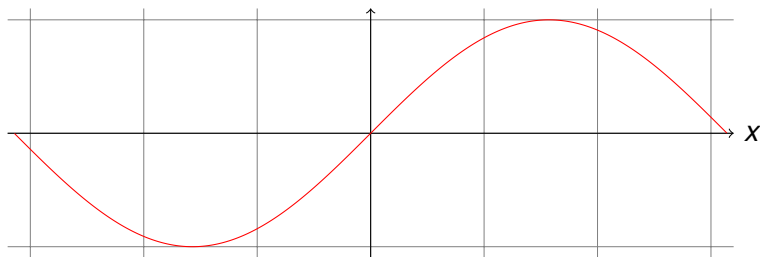
- how do you represent a real number ? (infinite object)

Motivating example

Example (Sine function)

Given $x \in \mathbb{R}$, compute $\sin(x)$.

⇒ “clearly \sin is computable:”



But...

- how do you represent a real number ? (infinite object)
- what is a program working on them ?

A classical approach

Computable analysis

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- a real number is a program:

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Computable analysis

- a real number is a program: it computes arbitrary approximations
- a function is a program transformation: it transforms one approximation into another
- Intuition: can draw the graph of a function with arbitrary zoom
- Very analytic, approximation theory
- Can lift Turing complexity to real functions
- Has a nice theory of open sets

Computable real

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Example (Non-computable real)

$$r = \sum_{n=0}^{\infty} d_n 2^{-n}$$

where

$$d_n = 1 \Leftrightarrow \text{the } n^{\text{th}} \text{ Turing Machine halts on input } n$$

Computable function

Definition (Computable function)

$f : [a, b] \rightarrow \mathbb{R}$ is computable iff $\exists m, \psi$ computable functions s.t $\forall n \in \mathbb{N}$:

- $\forall x, y, |x - y| \leq 2^{-m(n)} \Rightarrow |f(x) - f(y)| \leq 2^{-n}$ ► effective continuity
- $\forall r \in \mathbb{Q}, |\psi(r, n) - f(r)| \leq 2^{-n}$ ► approximability

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Example (Counter-Example)

$f(x) = \lceil x \rceil$ ► not continuous

Thoughts on the model

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Question

Can we give a purely analog model of computation ?

GPAC

General Purpose Analog Computer

- by Claude Shannon (1941)

GPAC

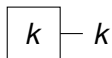
General Purpose Analog Computer

- by Claude Shannon (1941)
- idealization of an analog computer: Differential Analyzer

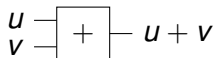
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General Purpose Analog Computer

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- circuit built from:



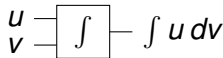
A constant unit



An adder unit



An multiplier unit



An integrator unit

GPAC: beyond the circuit approach

Theorem

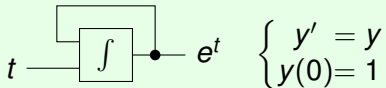
y is generated by a GPAC iff it is a component of the solution $y = (y_1, \dots, y_d)$ of the ordinary differential equation (ODE):

$$\begin{cases} y'(t) = p(y(t)) \\ y(t_0) = y_0 \end{cases}$$

where p is a vector of polynomials.

GPAC: examples

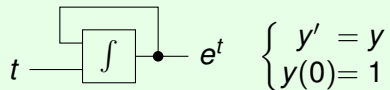
Example (One variable, linear system)



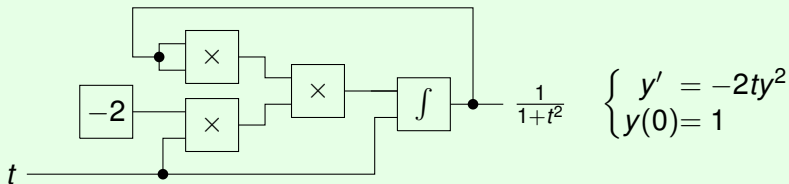
$$\begin{cases} y' = y \\ y(0) = 1 \end{cases}$$

GPAC: examples

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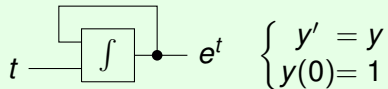


Example (One variable, nonlinear system)

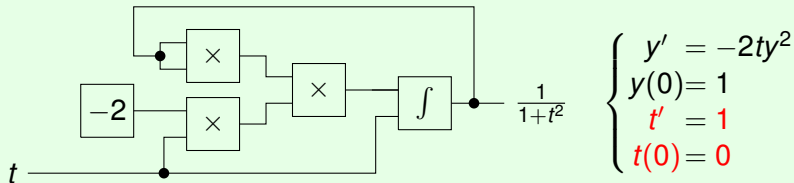


GPAC: examples

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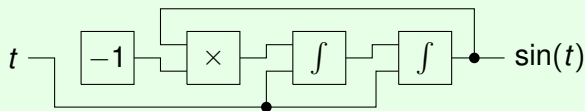


Example (Two variable, nonlinear system)



GPAC: examples

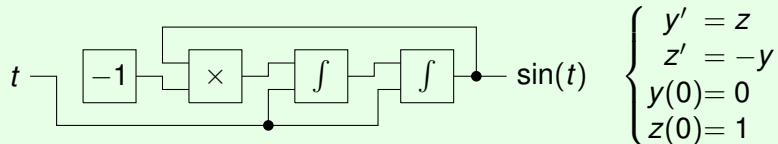
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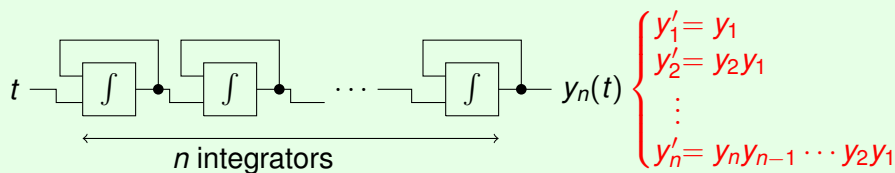
$$\begin{cases} y' = z \\ z' = -y \\ y(0) = 0 \\ z(0) = 1 \end{cases}$$

GPAC: examples

Example (Two variables, linear system)

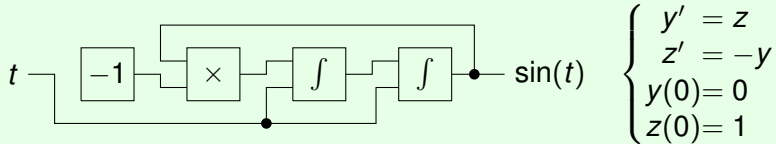


Exercice (Tear your mind apart)

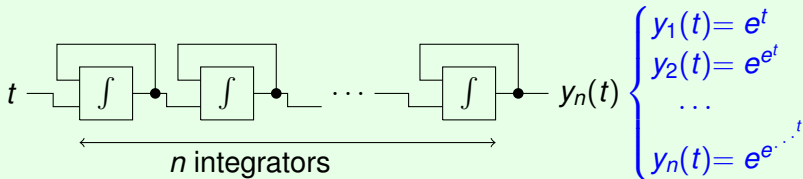


GPAC: examples

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Exercice (Tear your mind apart)



Slight issue is...

- the GPAC generated functions are analytical

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- the GPAC generated functions are analytical
- the computable functions from Computable Analysis are “only” continuous

Question

Can we bridge the gap ? Why should we ?

The case of discrete computations

Many models:

- Recursive functions
- Turing machines
- λ -calculus
- circuits
- ...

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All reasonable discrete models of computation are equivalent.

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All reasonable discrete models of computation are equivalent.

Can be extended to complexity when relevant.

GPAC: back to the basics

Definition

f is **generated** by a GPAC iff it is a component of the solution y of:

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satisfies $f(x) = \lim_{t \rightarrow \infty} y_1(t)$.

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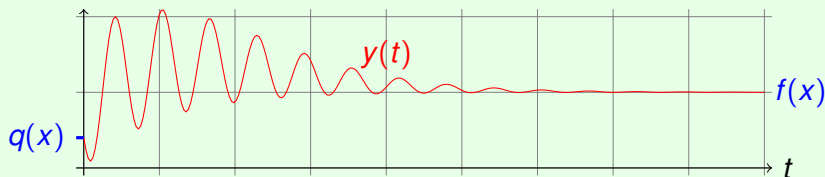
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Example



Computable Analysis = GPAC ? (again)

Theorem (Bournez, Campagnolo, Graça, Hainry)

f is GPAC-computable functions iff it is computable (in the sense of Computable Analysis).

Time Scaling

System	#1	#2
PIVP	$\begin{cases} y'(t) = p(y(t)) \\ y(1) = q(x) \end{cases}$	$\begin{cases} z'(t) = u(t)p(z(t)) \\ u'(t) = u(t) \\ z(t_0) = q(x) \\ u(1) = 1 \end{cases}$

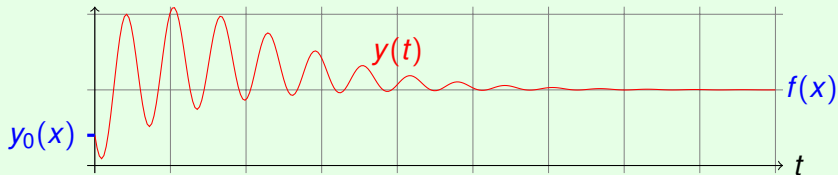
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Remark

Same curve, different speed: $u(t) = e^t$ and $z(t) = y(e^t)$

Example



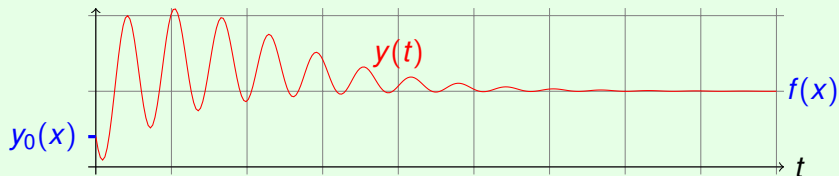
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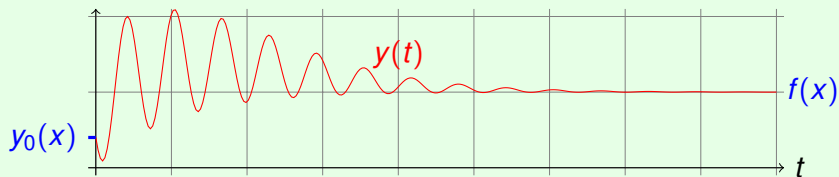
Example



Time Scaling

PIVP	$y' = p(y)$	$z(t) = y(e^t) \rightarrow \begin{cases} z' = up(z) \\ u' = u \end{cases}$
Computed Function	Same	
Convergence	Exponentially faster	

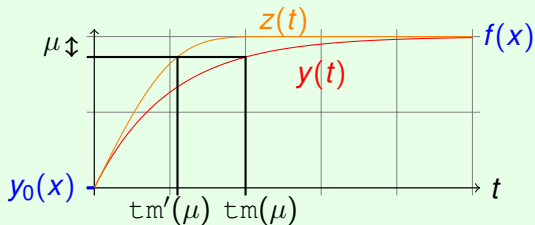
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Computed Function	Same	
Time for precision μ	$\tau_m(\mu)$	$\tau_m'(\mu) = \log(\tau_m(\mu))$

Example



$$\|y_1(\tau_m(\mu)) - f(x)\| \leq \mu$$

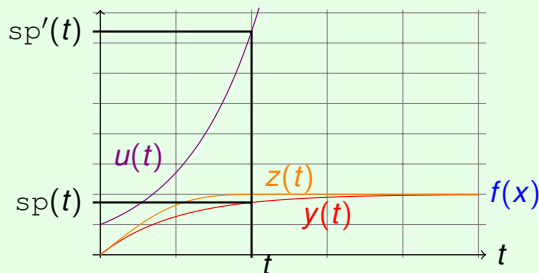
Remark

τ_m is not a good measure of complexity.

Time Scaling

PIVP	$y' = p(y)$	$z(t) = y(e^t) \rightarrow \begin{cases} z' = up(z) \\ u' = u \end{cases}$
Computed Function		Same
Time for precision μ	$\tau_m(\mu)$	$\tau_m'(\mu) = \log(\tau_m(\mu))$
Bounding box for PIVP at time t	$sp(t)$	$sp'(t) = \max(sp(e^t), e^t)$

Example



$$sp(t) = \sup_{\xi \in [1, t]} \|y(\xi)\|$$

$$sp'(t) = \sup_{\xi \in [1, t]} \|z(\xi), u(\xi)\|$$

Time Scaling

PIVP	$y' = p(y)$	$z(t) = y(e^t) \rightarrow \begin{cases} z' = up(z) \\ u' = u \end{cases}$
Computed Function	Same	
Time for precision μ	$t_m(\mu)$	$t_m'(\mu) = \log(t_m(\mu))$
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Remark

- $t_m(\mu)$ and $sp(t)$ depend on the convergence rate

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Bounding box for PIVP at precision μ	$sp(t_m(\mu))$	$\max(sp(t_m(\mu)), t_m(\mu))$

Remark

- $t_m(\mu)$ and $sp(t)$ depend on the convergence rate
- $sp(t_m(\mu))$ seems not

Proper Measures

Proper measures of “complexity”:

- time scaling invariant
- property of the curve

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Proper measures of “complexity”:

- time scaling invariant
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Possible choices:

- Bounding Box at precision $\mu \Rightarrow$ **Ok but geometric interpretation ?**
- Length of the curve until precision $\mu \Rightarrow$ **Much more intuitive**

Complexity based on the length of the curve

Definition

f is **poly-computable** by a GPAC iff $\exists p, q$ polynomials s.t. $\forall x \in \mathbb{R}$, the solution $y = (y_1, \dots, y_d)$ of:

$$\begin{cases} y'(t) = p(y(t)) \\ y(t_0) = q(x) \end{cases}$$

satisfies that $\|f(x) - y_1(t)\| \leq e^{-\mu}$ when $\ell(t) \geq \text{len}(\|x\|, \mu)$ where:

- len is a polynomial
- $\ell(t)$ is the length of the curve y from 0 to t

An equivalent classes

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satisfies that:

- $\|f(x) - y_1(t)\| \leq e^{-\mu}$ when $t \geq \text{poly}(\|x\|, \mu)$
- $\|y(t)\| \leq \text{poly}(\|x\|, t)$

Equivalence theorem

Theorem

f is poly-computable if and only if it is computable in polytime in the sense of Computable Analysis.

Conclusion

- Complexity theory for a continuous model of computation
- Natural, machine-independent definition of real computable functions

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Future work:

- Other complexity classes (time or space)
- Better understand how the restrictions constraint the complexity

Questions ?

- Do you have any questions ?