

FUNCTIONAL ABSTRACTION  
FOR PROGRAMMING  
MULTI-LEVEL ARCHITECTURES:  
FORMALISATION AND IMPLEMENTATION

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PH.D. DEFENSE



UNIVERSITÉ ———  
— PARIS-EST

# Table of Contents

- ① Introduction
- ② The MULTI-ML language
- ③ Type system
- ④ Implementation
- ⑤ Conclusion

# Table of Contents

- 1 Introduction
  - The world of parallel computing
  - Parallel programming models
- 2 The MULTI-ML language
- 3 Type system
- 4 Implementation
- 5 Conclusion

# The world of parallel computing

## Simulations:

Fluid simulation  
3D Visualisation

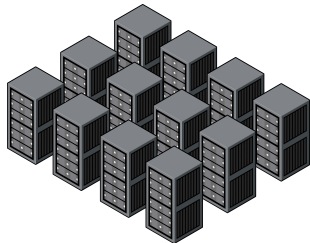
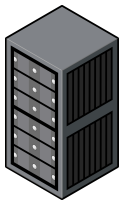
## Big-Data:

*IoT*  
Social Networking  
Data science

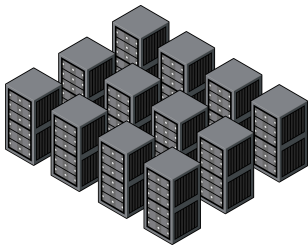
## Symbolic computation:

Model-Checking  
Formal computing

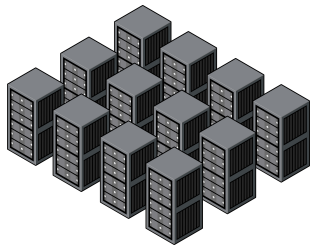
Super-computer



# Parallel computing over the years



# Parallel computing over the years

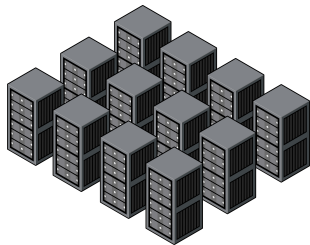


Shared memory

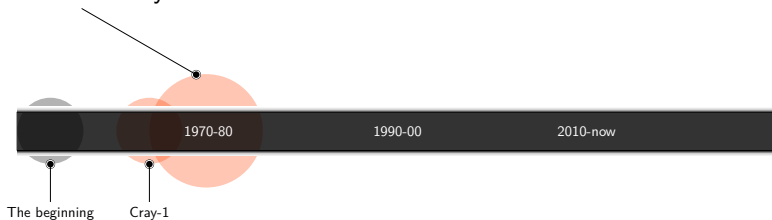


The beginning

# Parallel computing over the years



Shared memory

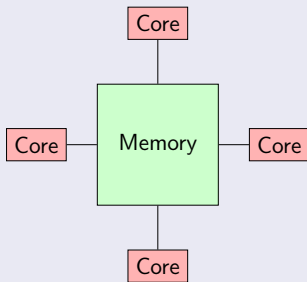


# Shared memory models



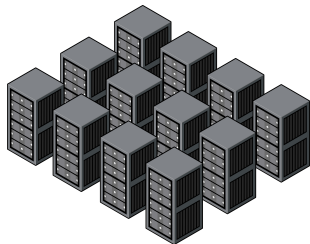
Characterised by:

- A shared memory
- Integrated network (NUMA)
- OPENMP/PTHREAD (C, FORTRAN)

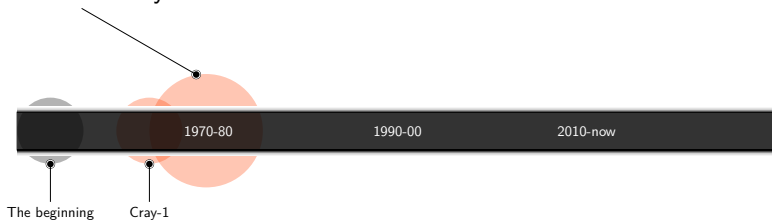




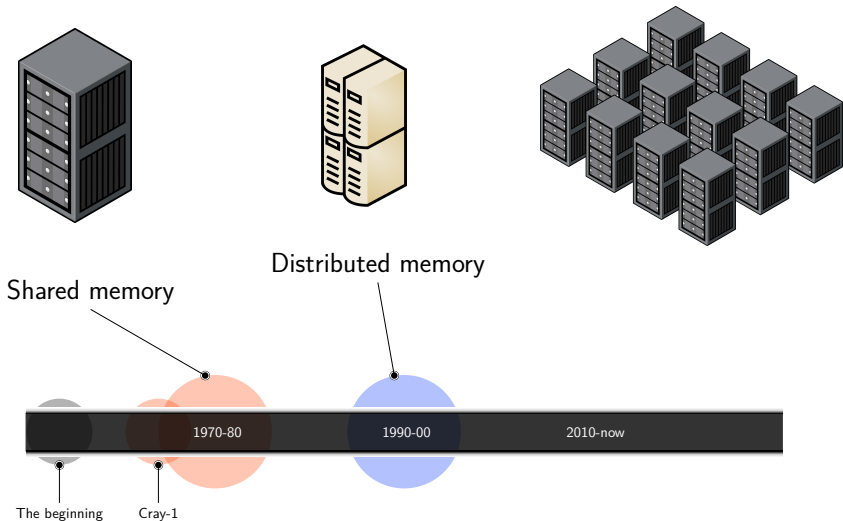
# Parallel computing over the years



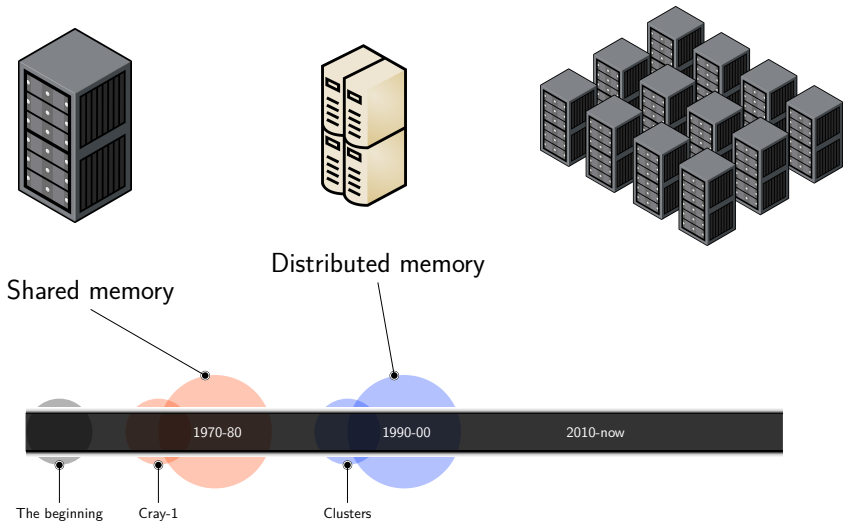
Shared memory



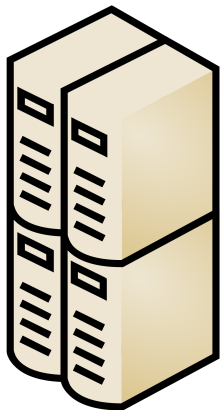
# Parallel computing over the years



# Parallel computing over the years

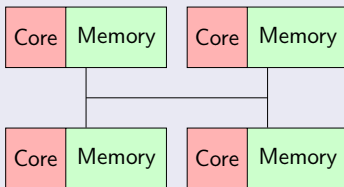


# Distributed computing

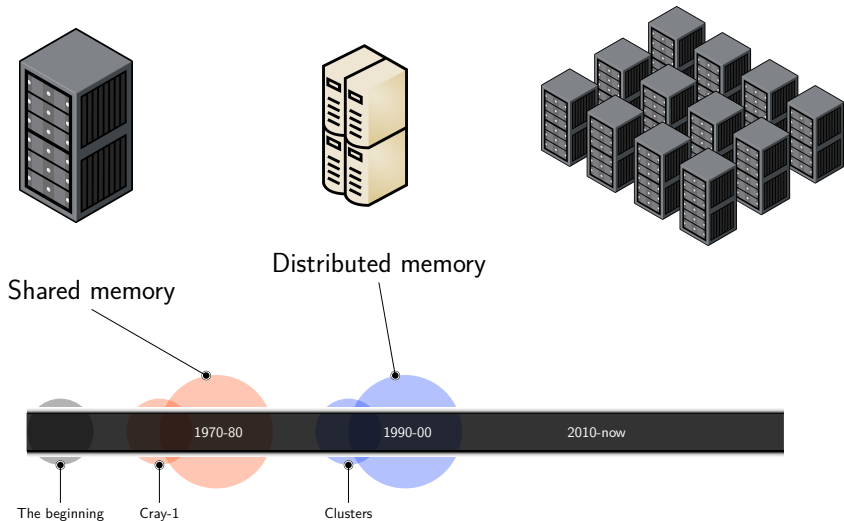


## Characterised by:

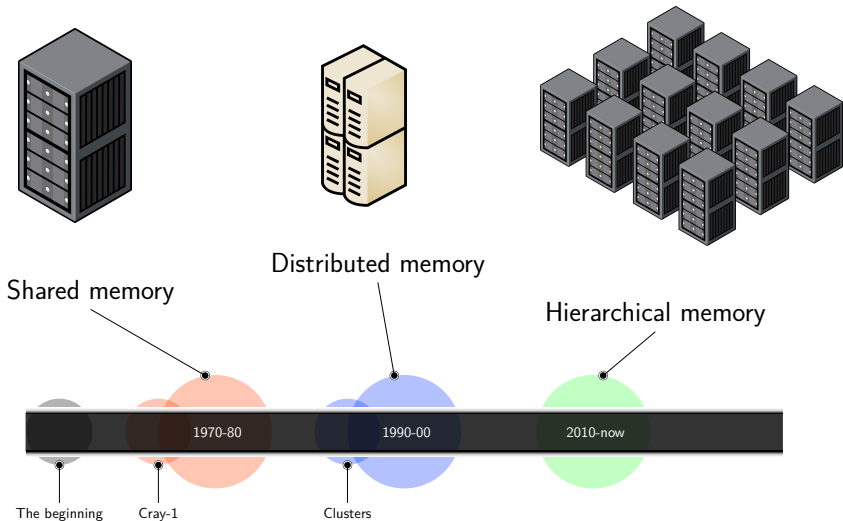
- Interconnected units
- Distributed memory
- Communication network
- MPI/map-reduce



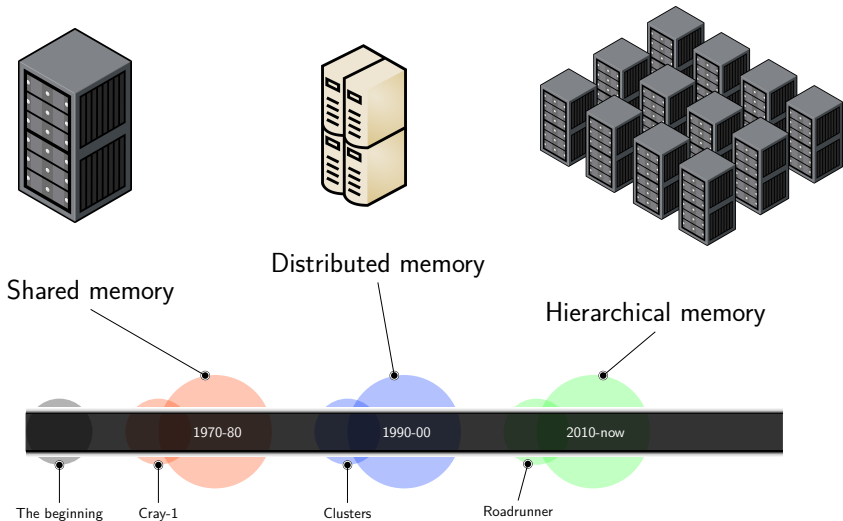
# Parallel computing over the years



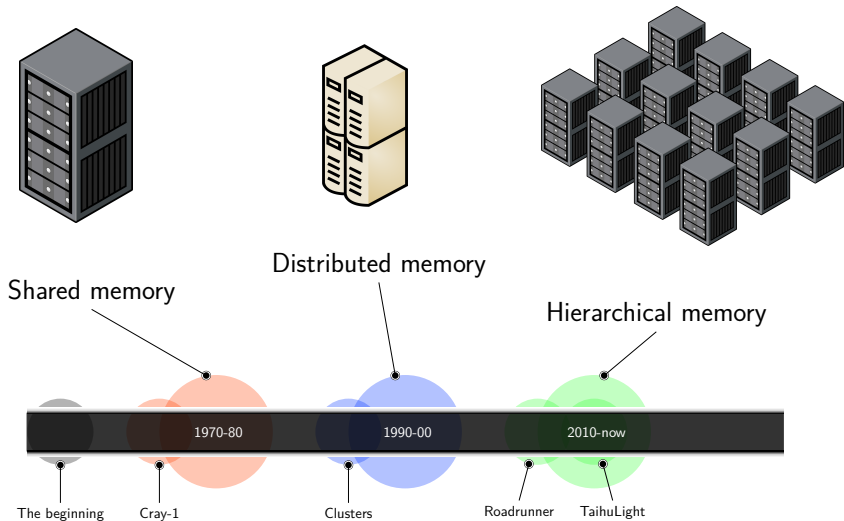
# Parallel computing over the years



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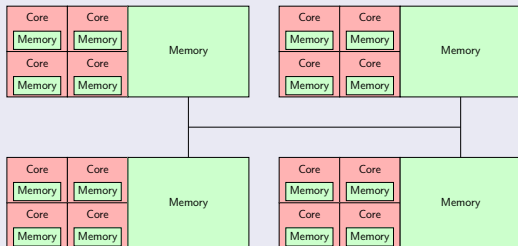
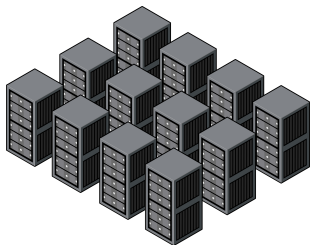




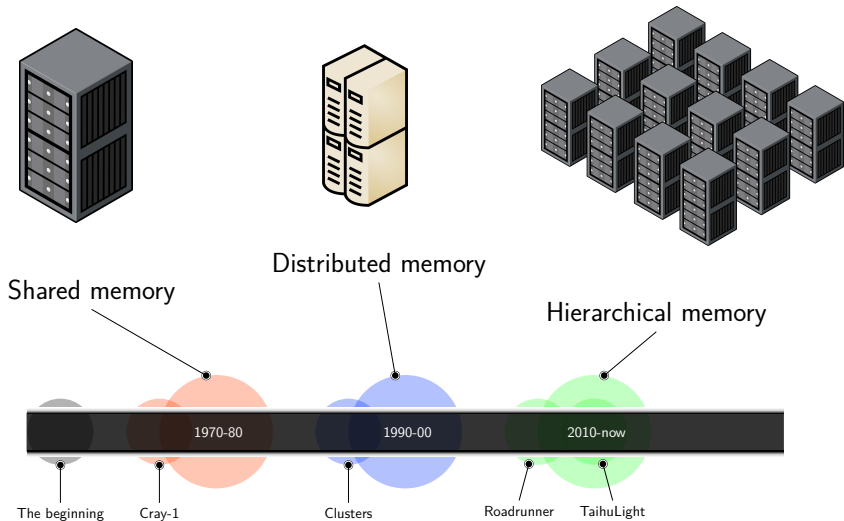
# Hierarchical architectures

Characterised by:

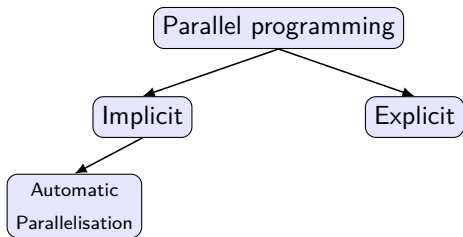
- Interconnected units
- Both shared and distributed memories
- Hierarchical memories



# Parallel computing over the years



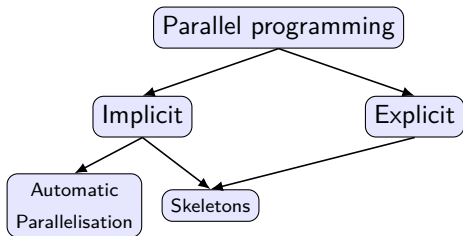
# Parallel programming models



## Automatic Parallelisation:

- + Easy
  - + Transparent
  - Limited
  - "Naive"
- Par4All
  - Intel C++ compiler
  - Vienna Fortran compiler

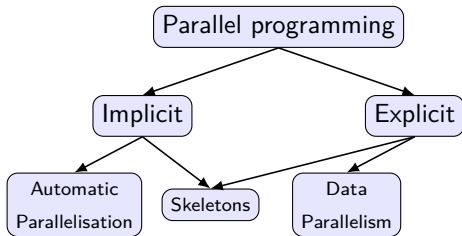
# Parallel programming models



## Skeletons:

- + Easy
  - + Structured
  - Difficult to extend
  - Cost model
- SKML
  - SKETO
  - Muesli

# Parallel programming models

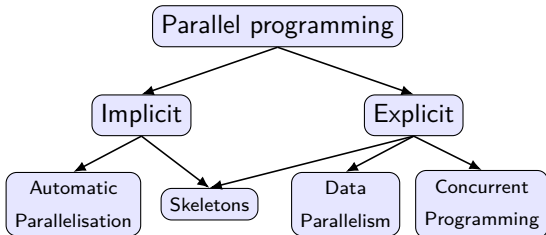


## Data Parallelism:

- + Structured
- + Patterns
- Limited
- Complex

- OPENMP
- SAC
- CUDA

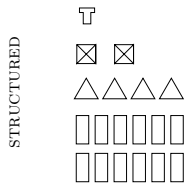
# Parallel programming models



## Concurrent Programming:

- + Flexible
  - + Powerful
  - Complex
  - Error prone
- MPI
  - PTHREAD
  - ERLANG/JOCAML

## Why structured parallelism ?



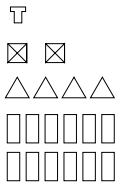
Pieces (Data)

Workers (Processes)

House (Results)

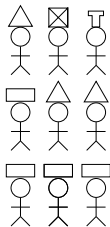
## Why structured parallelism ?

STRUCTURED



Pieces (Data)

+



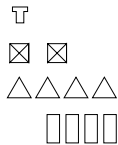
Workers (Processes)

House (Results)



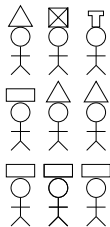
## Why structured parallelism ?

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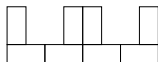
Pieces (Data)

+



Workers (Processes)

→



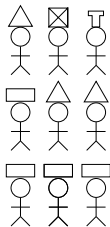
House (Results)

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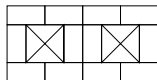
STRUCTURED



+



→



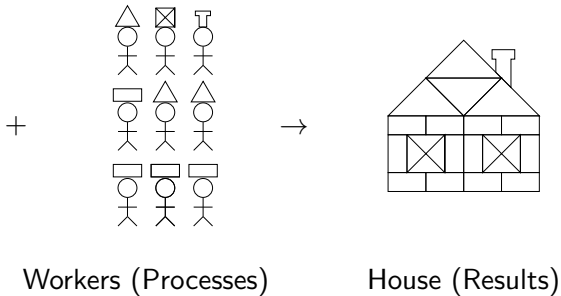
Pieces (Data)

Workers (Processes)

House (Results)

## Why structured parallelism ?

STRUCTURED



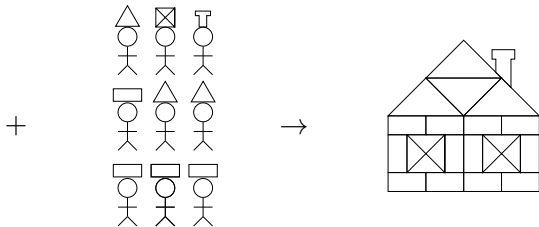
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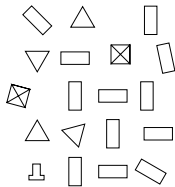


Pieces (Data)

Workers (Processes)

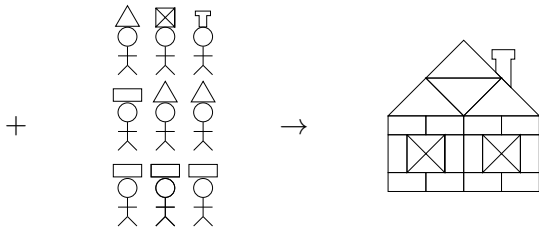
House (Results)

UNSTRUCTURED



# Why structured parallelism ?

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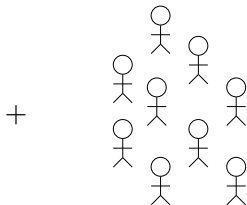
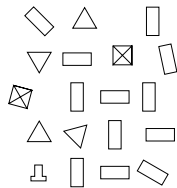


Pieces (Data)

Workers (Processes)

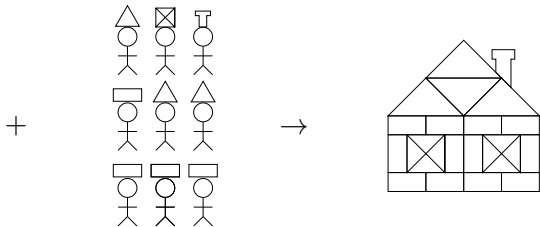
House (Results)

UNSTRUCTURED



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STRUCTURED

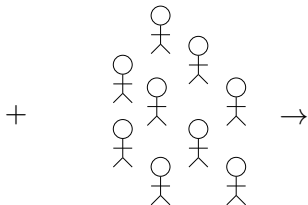
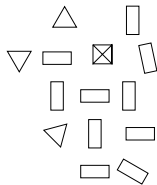


Pieces (Data)

Workers (Processes)

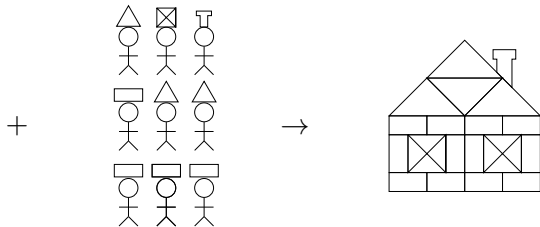
House (Results)

UNSTRUCTURED



# Why structured parallelism ?

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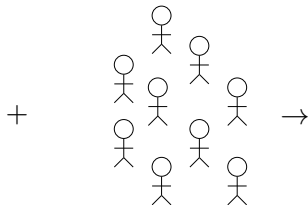
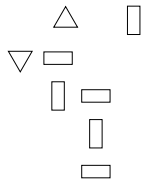


Pieces (Data)

Workers (Processes)

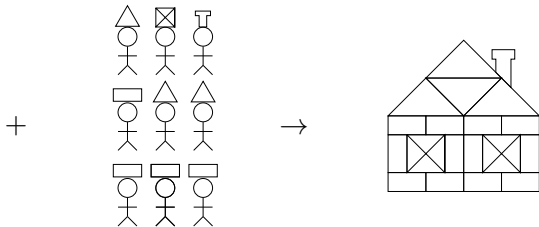
House (Results)

UNSTRUCTURED



# Why structured parallelism ?

STRUCTURED

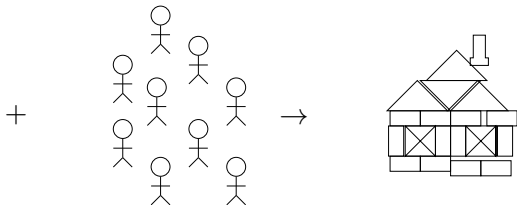


Pieces (Data)

Workers (Processes)

House (Results)

UNSTRUCTURED

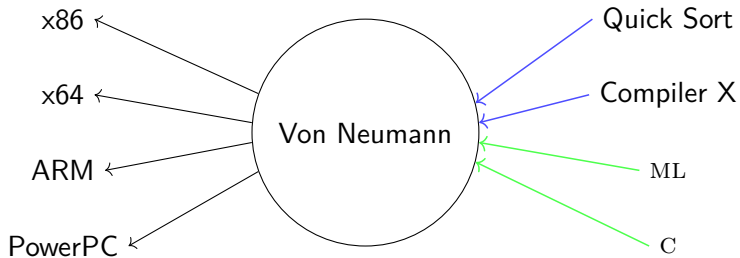




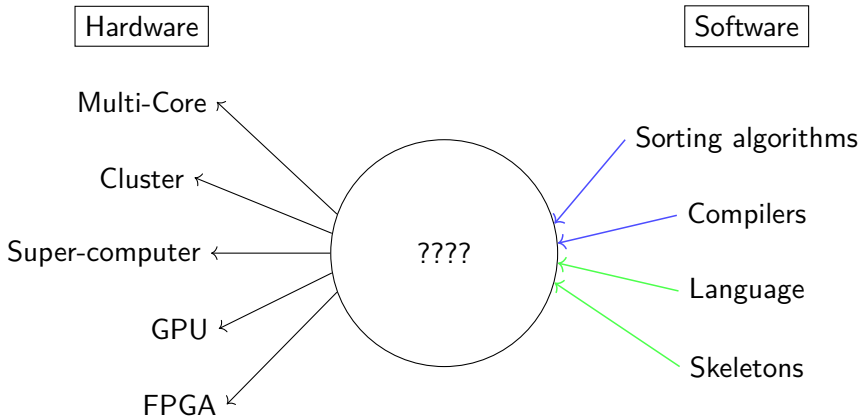
## A sequential bridging model

Hardware

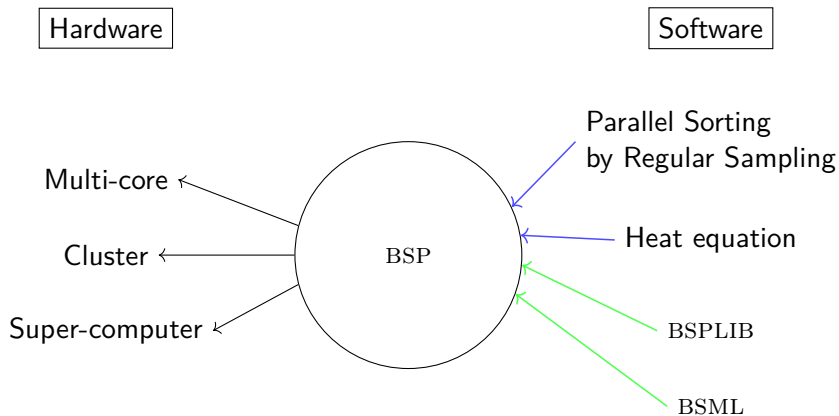
Software



## A parallel bridging model



# A parallel bridging model



# Bulk Synchronous Parallelism

## The BSP computer

Defined by:

# Bulk Synchronous Parallelism

## The BSP computer

Defined by:

- $p$  pairs CPU/memory

# Bulk Synchronous Parallelism

## The BSP computer

Defined by:

- $p$  pairs CPU/memory
- Communication network

# Bulk Synchronous Parallelism

## The BSP computer

Defined by:

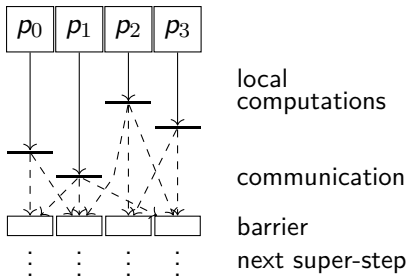
- $p$  pairs CPU/memory
- Communication network
- Synchronisation unit

# Bulk Synchronous Parallelism

## The BSP computer

Defined by:

- $p$  pairs CPU/memory
- Communication network
- Synchronisation unit
- Super-steps execution





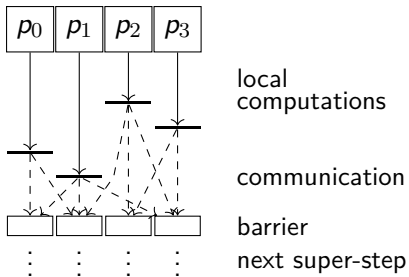
# Bulk Synchronous Parallelism

## The BSP computer

Defined by:

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## Properties:



# Bulk Synchronous Parallelism

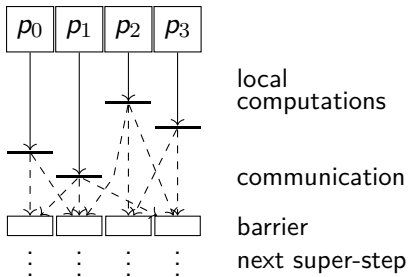
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## Properties:

- Deadlock-free



# Bulk Synchronous Parallelism

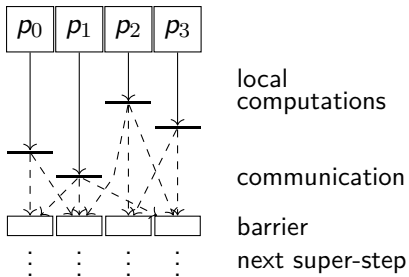
## The BSP computer

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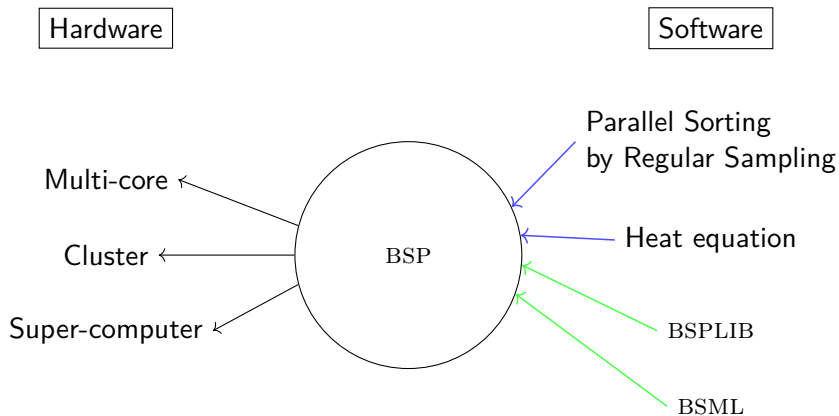
- $p$  pairs CPU/memory
- Communication network
- Synchronisation unit
- Super-steps execution

## Properties:

- Deadlock-free
- Predictable performances



# A parallel bridging model



# Bulk Synchronous ML

## What is BSML?

- Explicit BSP programming with a functional approach



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- Based upon ML and implemented over OCAML



# Bulk Synchronous ML

## What is BSML?

- Explicit BSP programming with a functional approach
- Based upon ML and implemented over OCAML
- Formal semantics  $\rightarrow$  computer-assisted proofs (COQ)



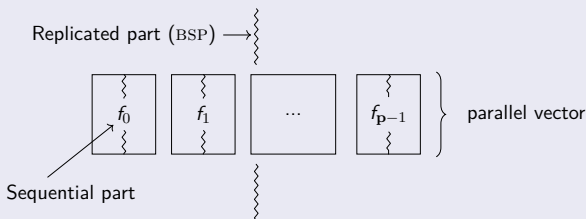
# Bulk Synchronous ML

## What is BSML?

- Explicit BSP programming with a functional approach
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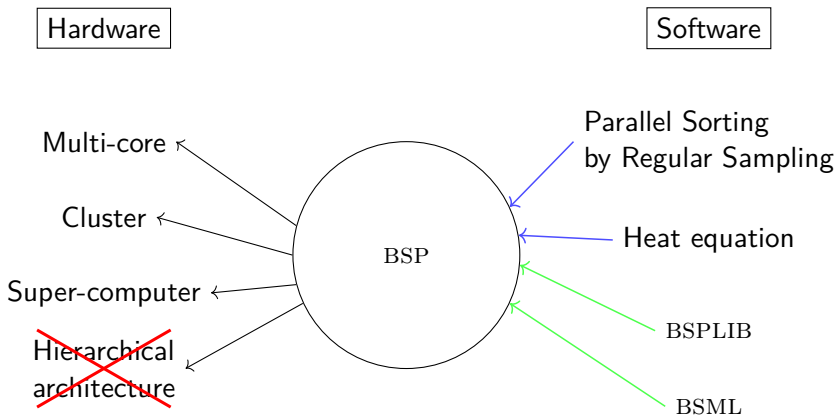
## Main idea

Parallel data structure  $\Rightarrow$  *parallel vector*:





# A parallel bridging model



# A parallel bridging model

Hardware

Software

Multi-core

Parallel Sorting  
by Regular Sampling

Cluster

Why ?

Heat equation

Super-computer

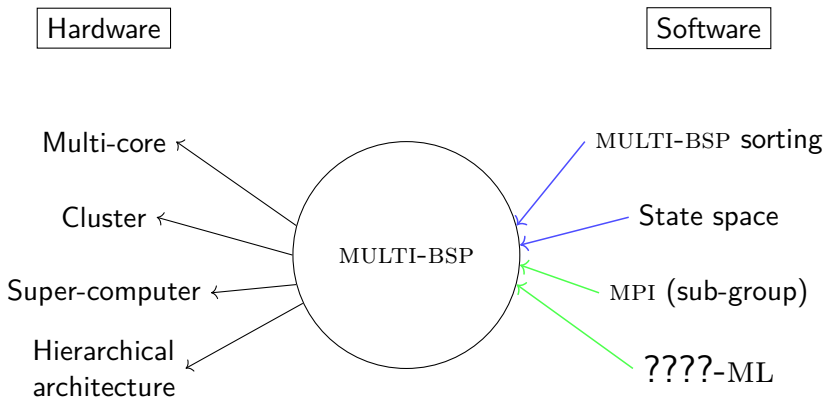
- Flat memories
- No sub-synchronisation

BSPLIB

~~Hierarchical  
architecture~~

BSML

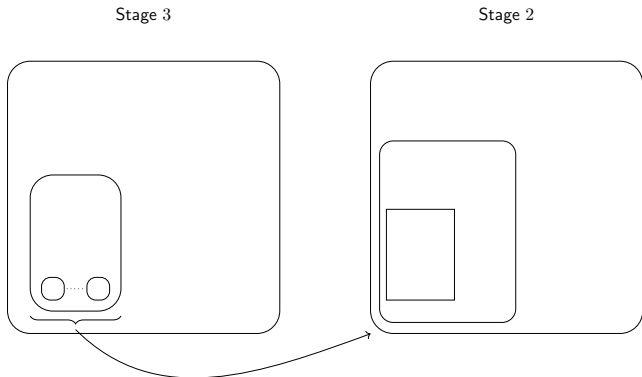
# A parallel bridging model



# What is MULTI-BSP?

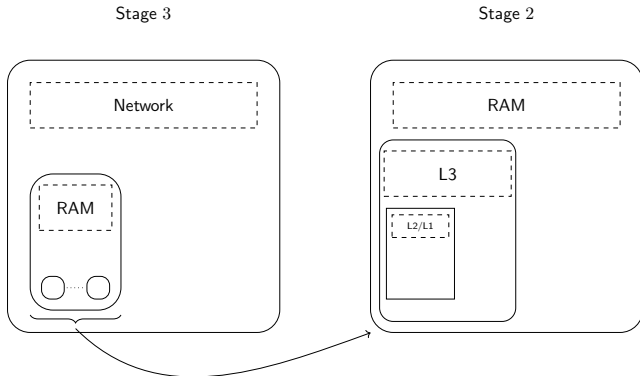
# What is MULTI-BSP?

- 1 A tree structure with nested components



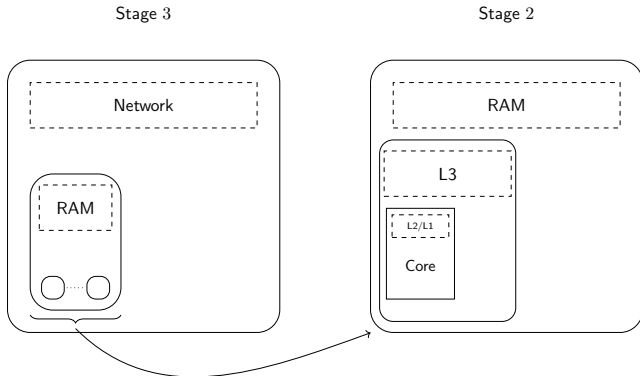
## What is MULTI-BSP?

- 1 A tree structure with nested components
- 2 Where nodes have a storage capacity



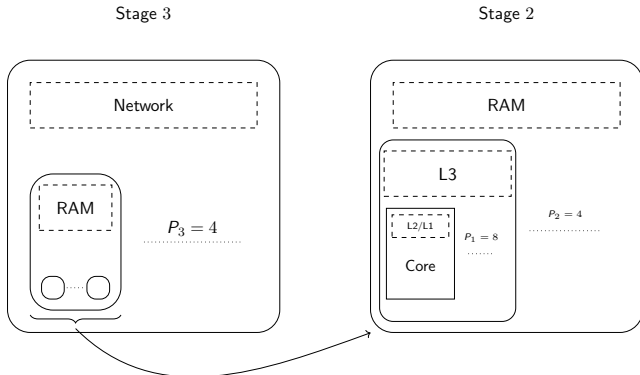
## What is MULTI-BSP?

- 1 A tree structure with nested components
- 2 Where nodes have a storage capacity
- 3 And leaves are processors



## What is MULTI-BSP?

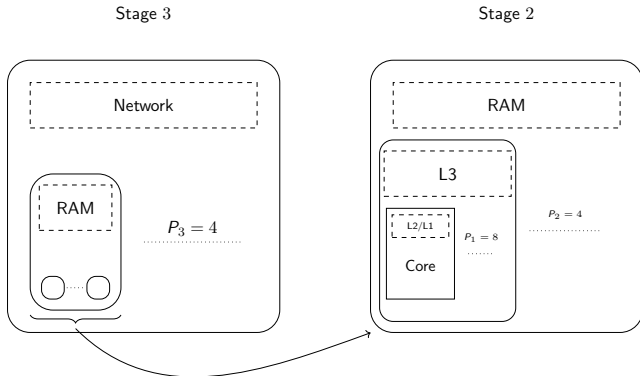
- 1 A tree structure with nested components
- 2 Where nodes have a storage capacity
- 3 And leaves are processors
- 4 With sub-synchronisation capabilities





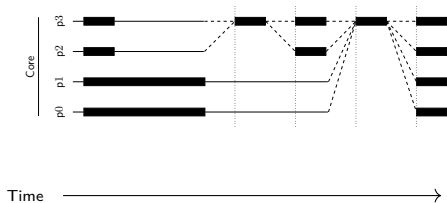
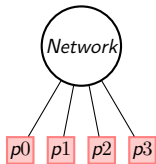
## What is MULTI-BSP?

- Stage 3: 4 nodes with a network access
- Stage 2: one node has 4 chips plus RAM
- Stage 1: one chip has 8 cores plus L3 cache
- Stage 0: one core with L1/L2 caches



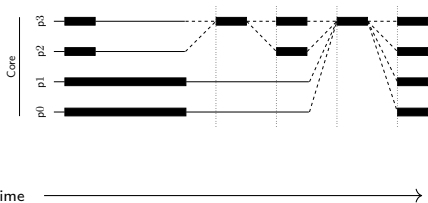
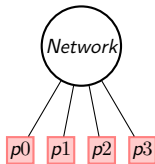
## BSP vs. MULTI-BSP

BSP

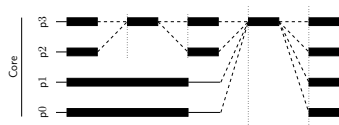
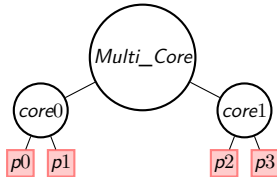


## BSP vs. MULTI-BSP

BSP



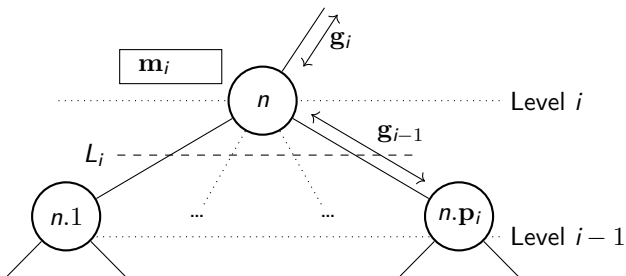
MULTI-BSP



# The MULTI-BSP model

## Execution model

A level  $i$  superstep is:

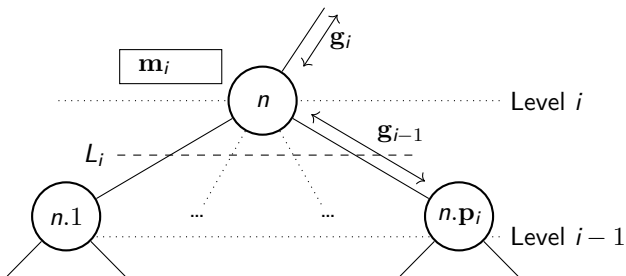


# The MULTI-BSP model

## Execution model

A level  $i$  superstep is:

- Level  $i-1$  executes code independently

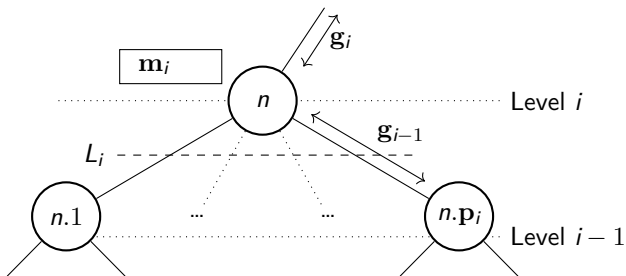


# The MULTI-BSP model

## Execution model

A level  $i$  superstep is:

- Level  $i-1$  executes code independently
- Exchanges information with the  $m_i$  memory

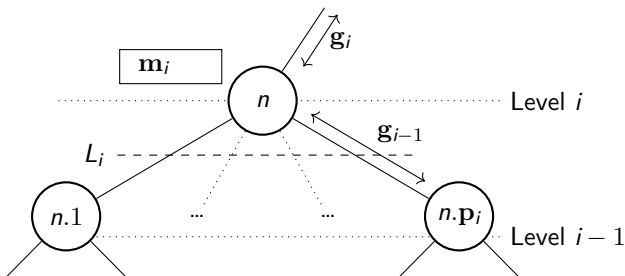


# The MULTI-BSP model

## Execution model

A level  $i$  superstep is:

- Level  $i-1$  executes code independently
- Exchanges information with the  $m_i$  memory
- Synchronises



# Table of Contents

- 1 Introduction
- 2 The MULTI-ML language
  - MULTI-ML overview
  - The MULTI-ML primitives
  - A code example
- 3 Type system
- 4 Implementation
- 5 Conclusion



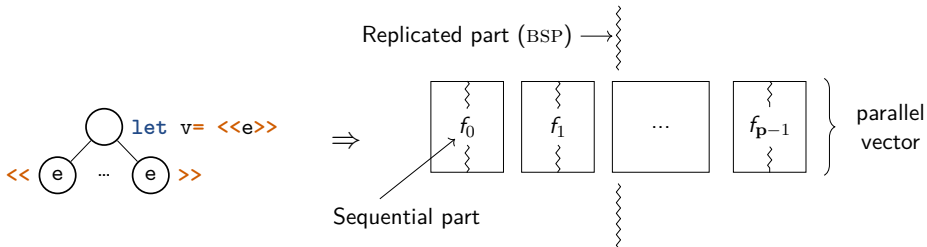
# The MULTI-ML language

## Basic ideas

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## Basic ideas

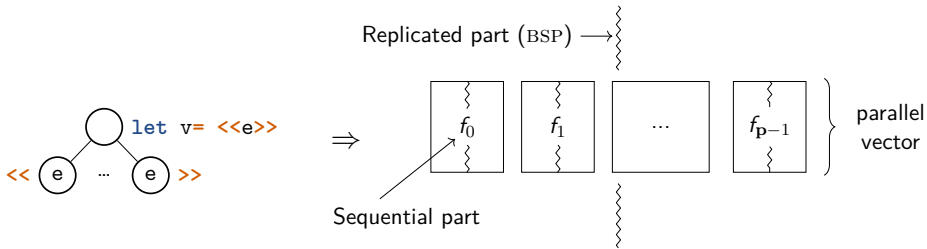
- BSML-like code on every stage of the MULTI-BSP architecture



# The MULTI-ML language

## Basic ideas

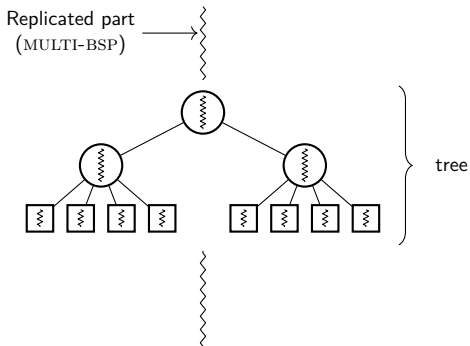
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- Specific syntax over ML: eases programming



# The MULTI-ML language

## Basic ideas

- BSML-like code on every stage of the MULTI-BSP architecture
- Specific syntax over ML: eases programming
- *Multi-functions* that recursively go through the MULTI-BSP tree



## MULTI-ML: Tree recursion

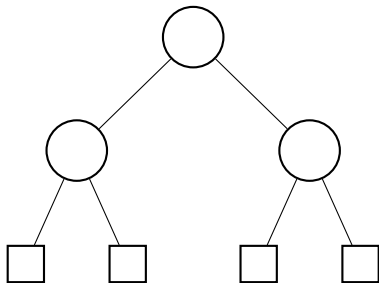
### Recursion structure

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let multi f [args]=  
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## MULTI-ML: Tree recursion

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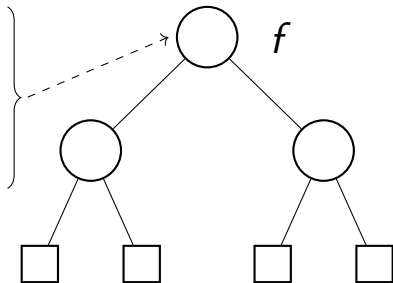
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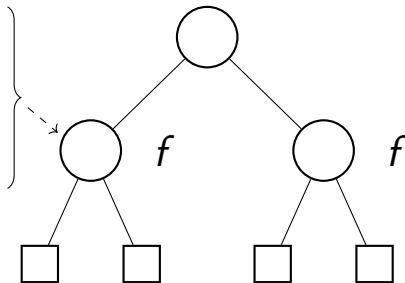
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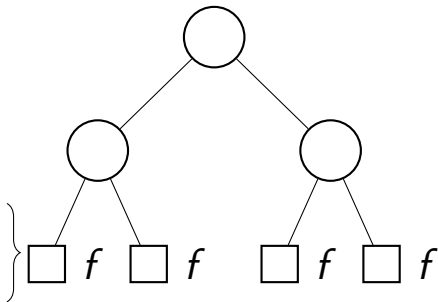




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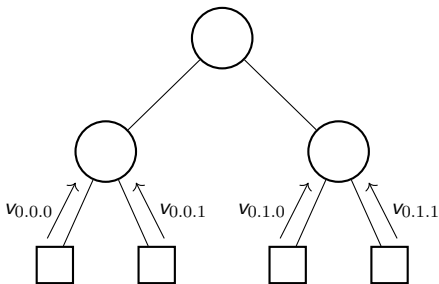
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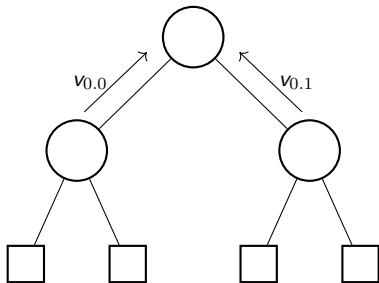
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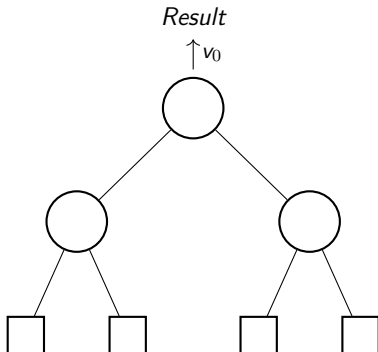
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## MULTI-ML: Tree construction

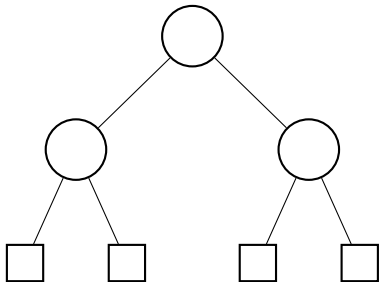
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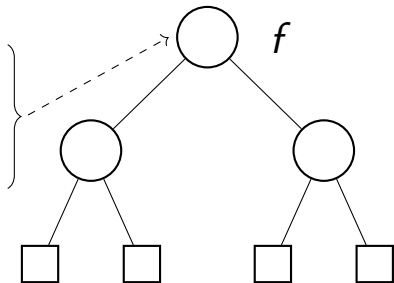
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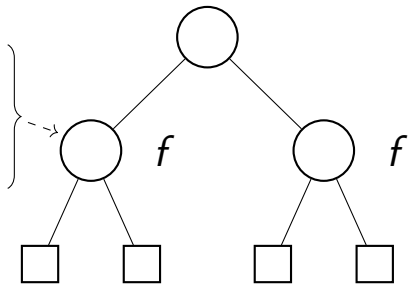
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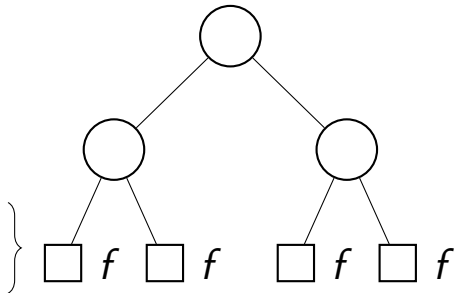




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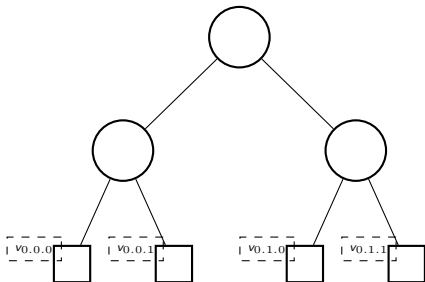
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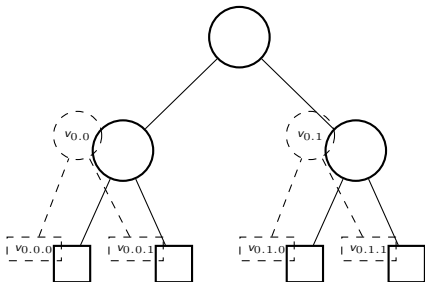
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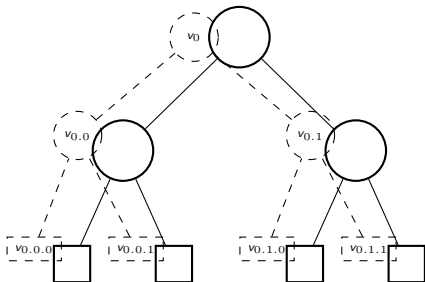
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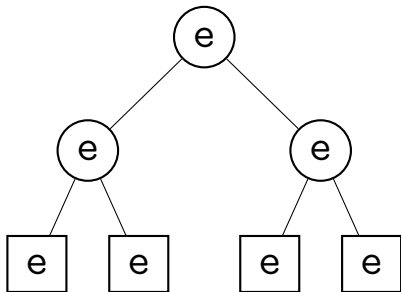
# Primitives

## Summary

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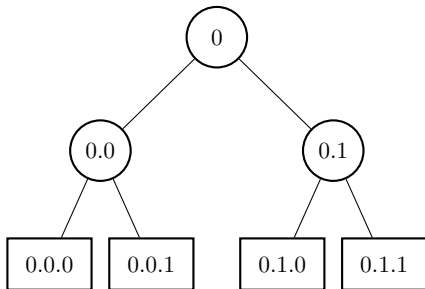
- `mktree e`



# Primitives

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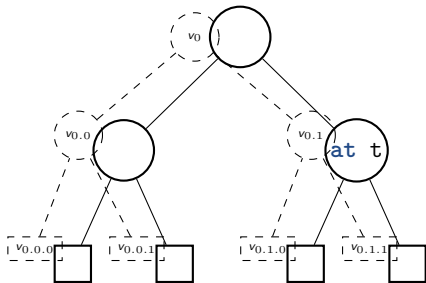
- `mktree e`
- `gid`



# Primitives

## Summary

- `mktree e`
- `gid`
- `at`

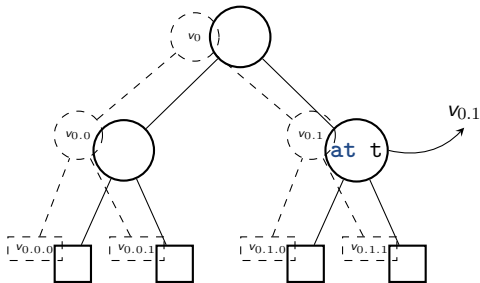




# Primitives

## Summary

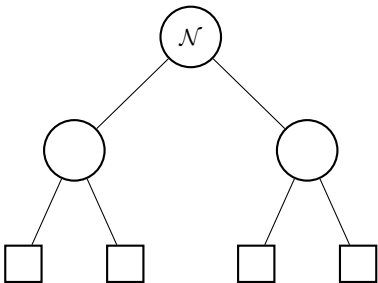
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# Primitives

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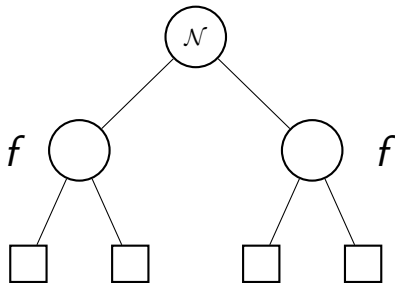
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# Primitives

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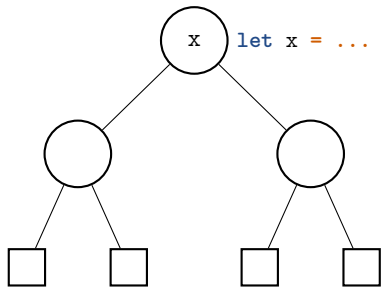
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# Primitives

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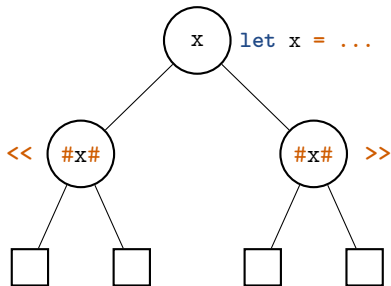
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# Primitives

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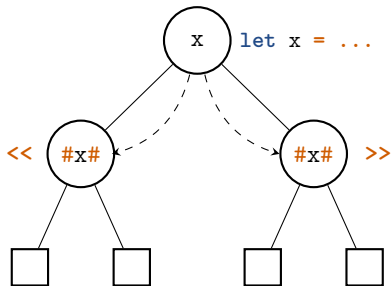
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# Primitives

## Summary

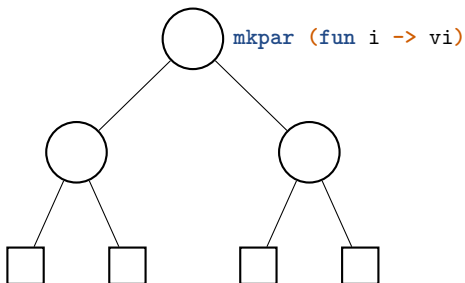
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# Primitives

## Summary

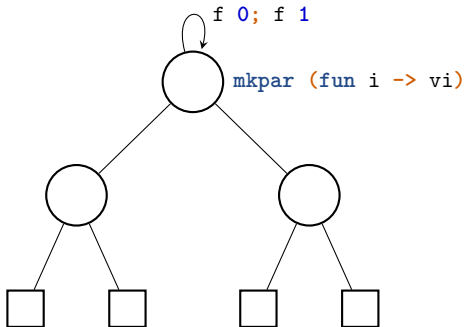
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# Primitives

## Summary

- `mktree e`
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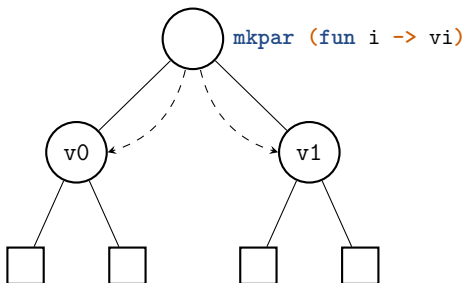




# Primitives

## Summary

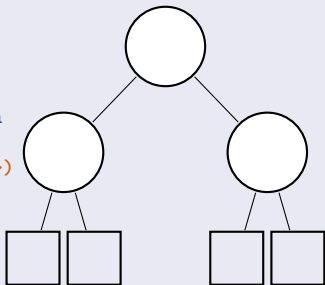
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## Code example

### Keep the intermediate results of the sum

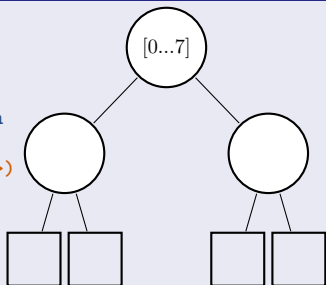
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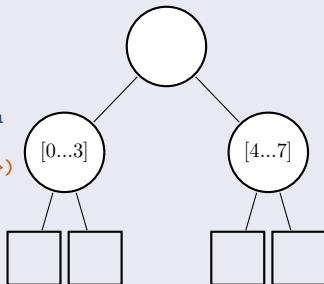
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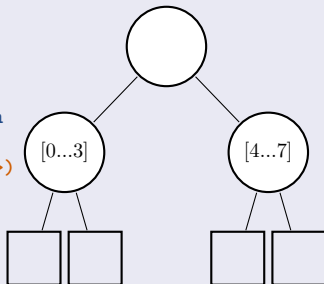
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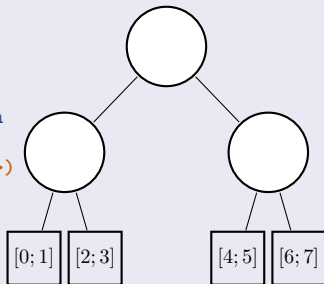
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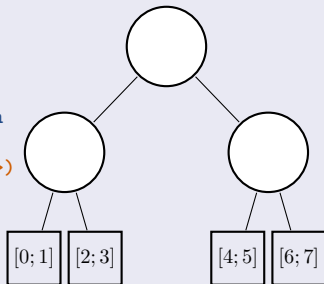
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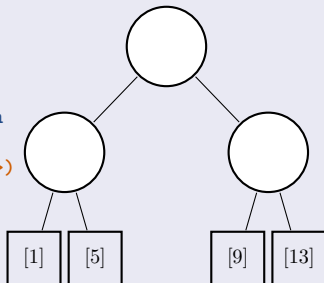
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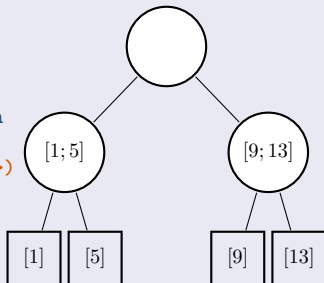




## Code example

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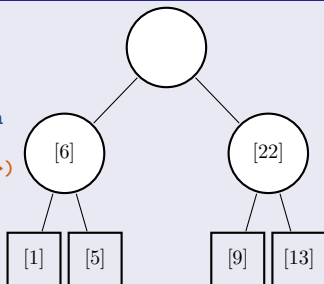
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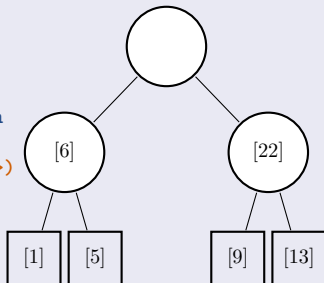
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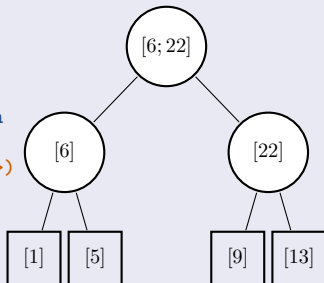
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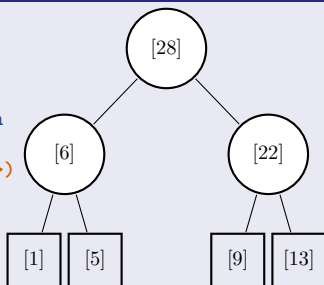
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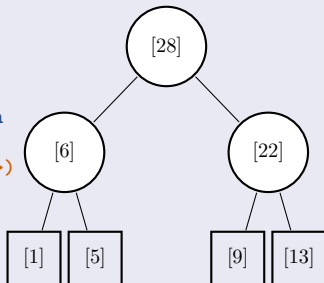
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# Table of Contents

- 1 Introduction
- 2 The MULTI-ML language
- 3 Type system**
  - Parallel program safety
  - The MULTI-ML typing system
- 4 Implementation
- 5 Conclusion

# Parallel program safety

## Parallel program safety

- Replicated coherency

## Replicated coherency

```
if random_bool () then
  multi_fct ()
else
  (fun _ -> ...) ()
```



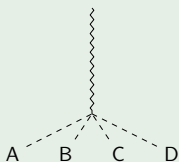
# Parallel program safety

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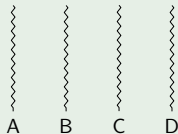
- Replicated coherency

Why ?

Replicat



or



## Parallel program safety

- Replicated coherency
- Level (memory) compatibility

## Level(memory) compatibility

```
<< let multi f x = ... >>  
let x = #y#  
let z = $v$
```

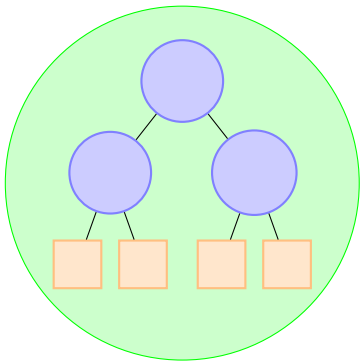
## Parallel program safety

- Replicated coherency
- Level (memory) compatibility
- Control parallel structure imbrication
  - vector
  - tree

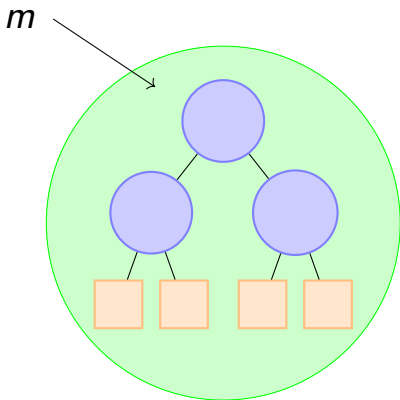
## Parallel structure imbrication

```
<< let v = << 1 >> in v >>  
let v = << 1 >> in << v >>
```

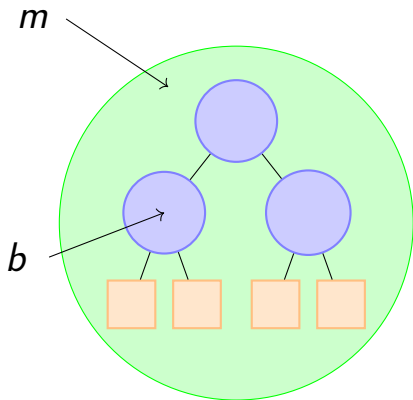
## Type localities



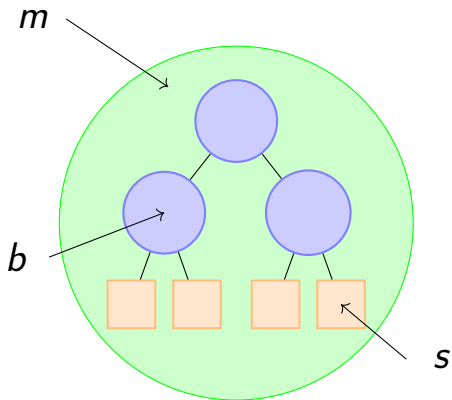
## Type localities



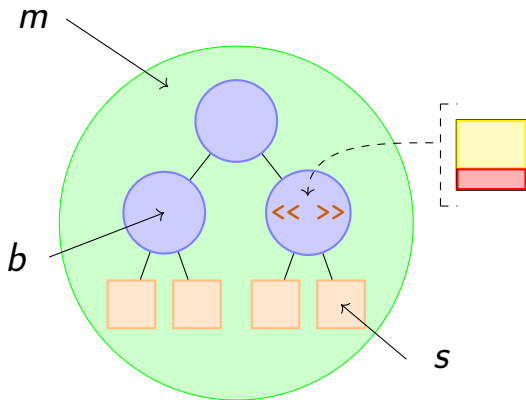
## Type localities



## Type localities

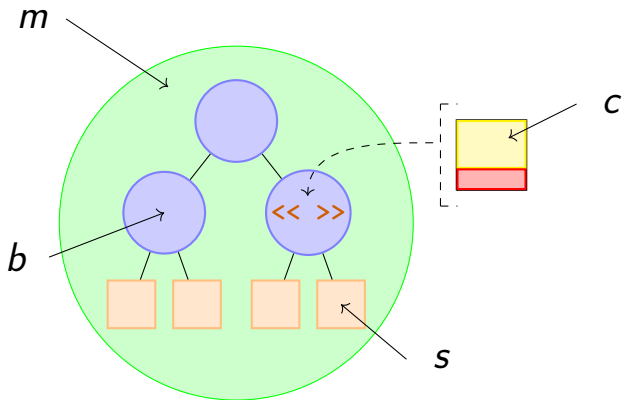


## Type localities

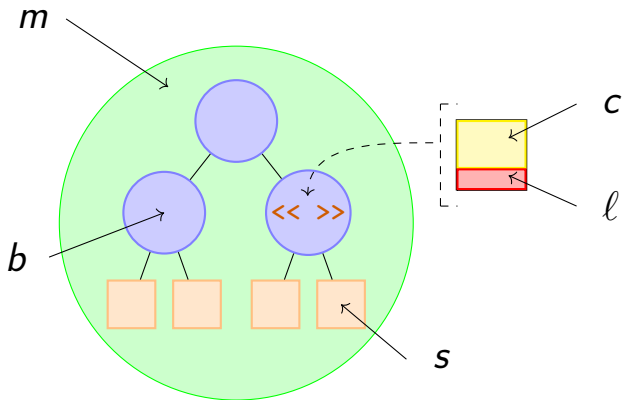




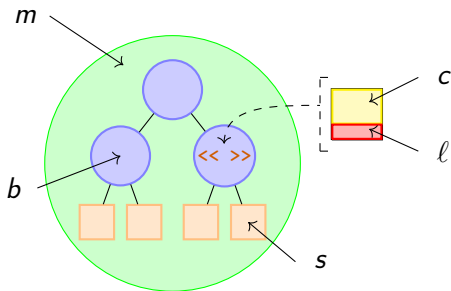
## Type localities



## Type localities



# Type annotations



## Type grammar

$\tau ::=$

- $\alpha_\pi$       *type variable*
- $\text{Base}_\pi$     *base type*
- $(\tau, \tau)_\pi$    *pair*
- $\tau \text{ Par}_b$     *vector*
- $\tau \text{ Tree}_\pi$    *tree*
- $(\tau \xrightarrow{\pi} \tau)_\pi$    *arrow type*

$\pi ::= m \mid b \mid c \mid l \mid s$

## Latent effect

$$(\tau \xrightarrow{\pi} \tau)_{\pi'}$$

Where  $\pi$  is the effect *emitted* by the evaluation and  $\pi'$  the locality of definition.

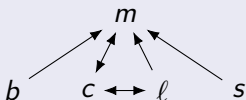
## A BSP function

```
#let f = fun x ->  
  let v = << ... >> in 1  
-: val f : ('a_z -(b)-> int_b)_m
```

$$f: ('a_z \xrightarrow{b} int_b)_m$$

## Accessibility: $\triangleleft$

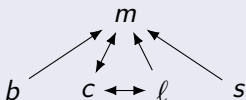
$m, c \triangleleft m$   
 $m, b \triangleleft b$   
 $m, l, c \triangleleft l$   
 $m, l, c \triangleleft c$   
 $m, s \triangleleft s$



$\lambda_2 \triangleleft \lambda_1$  : «  $\lambda_1$  can read in  $\lambda_2$  memory. »

## Accessibility: $\triangleleft$

$m, c \triangleleft m$   
 $m, b \triangleleft b$   
 $m, l, c \triangleleft l$   
 $m, l, c \triangleleft c$   
 $m, s \triangleleft s$



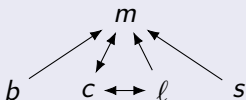
$\lambda_2 \triangleleft \lambda_1$  : «  $\lambda_1$  can read in  $\lambda_2$  memory. »

## Example:

$f: ('a_z \xrightarrow{b} int_b)_m$   
 $f \mathbf{1} \rightsquigarrow b \triangleleft m$

Accessibility:  $\triangleleft$

$m, c \triangleleft m$   
 $m, b \triangleleft b$   
 $m, l, c \triangleleft l$   
 $m, l, c \triangleleft c$   
 $m, s \triangleleft s$



$\lambda_2 \triangleleft \lambda_1$  : «  $\lambda_1$  can read in  $\lambda_2$  memory. »

Example:

$f: ('a_z \xrightarrow{b} int_b)_m$   
 $f \ 1 \rightsquigarrow b \triangleleft m$

Error

## Definability: ◀

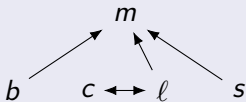
$s, b, m \blacktriangleleft m$

$b \blacktriangleleft b$

$l, c \blacktriangleleft c$

$l, c \blacktriangleleft l$

$s \blacktriangleleft s$



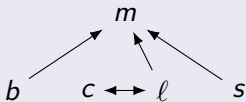
$\lambda_1 \blacktriangleleft \lambda_2 : \ll \lambda_1 \text{ can be defined in } \lambda_2 \text{ memory. } \gg$



# Definability

Definability: ◀

$s, b, m$  ◀  $m$   
 $b$  ◀  $b$   
 $l, c$  ◀  $c$   
 $l, c$  ◀  $l$   
 $s$  ◀  $s$



$\lambda_1$  ◀  $\lambda_2$  : «  $\lambda_1$  can be defined in  $\lambda_2$  memory. »

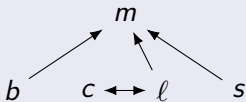
Example:

`<< let multi f x = ... >>`  $\rightsquigarrow$   $m$  ◀  $c$

# Definability

Definability: ◀

$s, b, m$  ◀  $m$   
 $b$  ◀  $b$   
 $l, c$  ◀  $c$   
 $l, c$  ◀  $l$   
 $s$  ◀  $s$



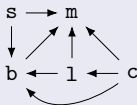
$\lambda_1$  ◀  $\lambda_2$  : «  $\lambda_1$  can be defined in  $\lambda_2$  memory. »

Example:

```
<< let multi f x = ... >>  $\rightsquigarrow$   $m$  ◀  $c$   
Error
```

### Propagation

This relation returns the prevailing effect among  $\varepsilon$  and  $\varepsilon'$ .



### Serialisation

Is it safe to communicate  $\tau_\pi$  to locality  $\Lambda$  ?

$\text{Seria}_\Lambda(\text{Base}_\pi) = \text{Base}_\Lambda$  if  $\text{Base} = \text{int}, \text{string}, \text{float}, \text{Bool}, \dots$

$\text{Seria}_\Lambda(\text{Base}_\pi) = \text{Fail}$  if  $\text{Base} = \text{i/o}, \dots$

$\text{Seria}_\Lambda(\tau_\pi) = \begin{cases} \tau_\Lambda, & \text{if } \pi \triangleleft \Lambda \\ \text{Fail}, & \text{otherwise} \end{cases}$

$\text{Seria}_\Lambda(\tau_\pi \text{ par}_b) = \text{Fail}$

# Formal properties

## Operational semantics

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- Big Step semantics (deterministic)

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## Operational semantics

- Big Step semantics (deterministic)
- Big Step semantics for diverging terms (mutually exclusive)
- Programs that “do not go wrong” :  $(\exists v. \Downarrow_p^{\mathcal{L}} v)$  or  $(\Downarrow_p^{\mathcal{L}} \infty)$

## Type safety of a MULTI-ML program

- Let  $e$  be an expression,
- $\Gamma$  a typing environment,
- and  $c$  a set of constraint.

Then:  $\Gamma \vdash e : \tau_\pi / \varepsilon[c]$  implies that  $e$  “does not go wrong” ( $e \Rightarrow_{safe}$ )

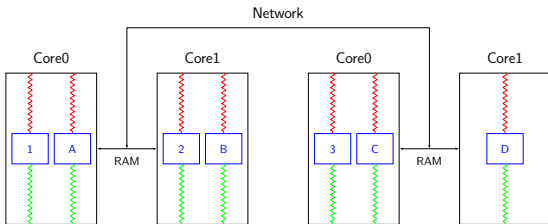
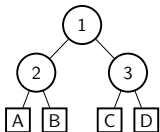


# Table of Contents

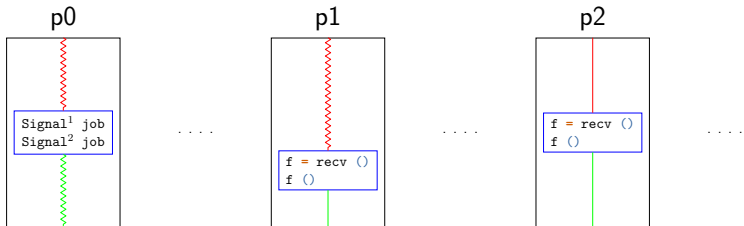
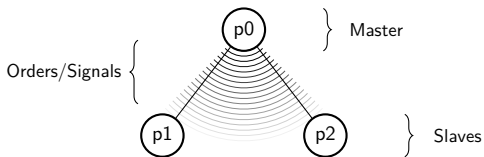
- 1 Introduction
- 2 The MULTI-ML language
- 3 Type system
- 4 Implementation**
  - Execution scheme
  - Parallel and sequential implementations
  - Benchmarks
- 5 Conclusion

## Execution scheme

- One process per leaf/node
- Distributed over physical cores



# Execution scheme



## Formal properties

### Correctness of a MULTI-ML program

If  $e \Rightarrow_{safe}$  and  $\mathcal{WF}(e)$  we have :  $\langle\langle [e]_M, \dots, [e]_M \rangle\rangle \Rightarrow_{safe}$

# Distributed implementation

## Module

- Communication library
- Based on operational semantics

## Current implementation

- MPI processes
- Distributed over physical cores
- Shared/Distributed memory

## Future implementations

- TCP/IP
- PTHREAD
- ...

# Sequential implementation

## Sequential simulator

- OCAML-like toplevel
- Test and debug
- Tree structure
- Hash tables to represent memories

```
#let multi tree f n =
  where node =
    let r = <<f ($pid$ + #n# + 1) >> in
      finally r (gid^"=>"^n)
  where leaf=
    (gid^"=>"^n);;

- : val f : int -> string tree = <multi-fun>
# (f 0)
o "0->0"
|
--o "0.0->1"
| |--> "0.0.0-> 2"
| |--> "0.0.1-> 3"
--o "0.1->2"
| |--> "0.1.0-> 3"
| |--> "0.1.1-> 4"
```

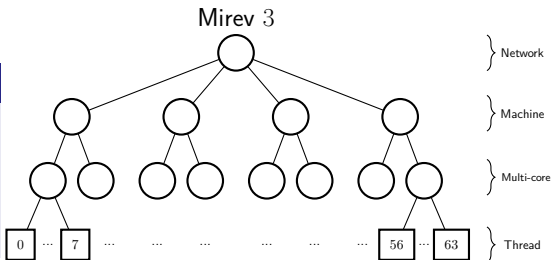
## Naive Eratosthenes sieve

- $\sqrt{(n)}$ th first prime numbers
- Based on scan
- Unbalanced

# Benchmarks

## Naive Eratosthenes sieve

- $\sqrt{(n)}$ th first prime numbers
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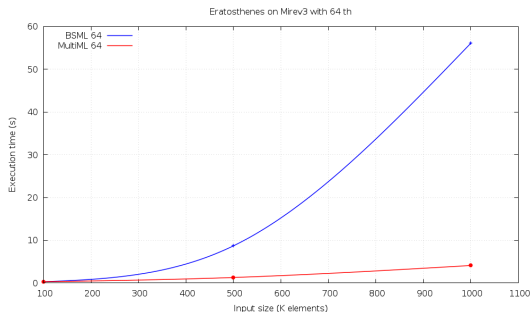




# Benchmarks

## Naive Eratosthenes sieve

- $\sqrt{(n)}$ th first prime numbers
- Based on scan
- Unbalanced



## Results

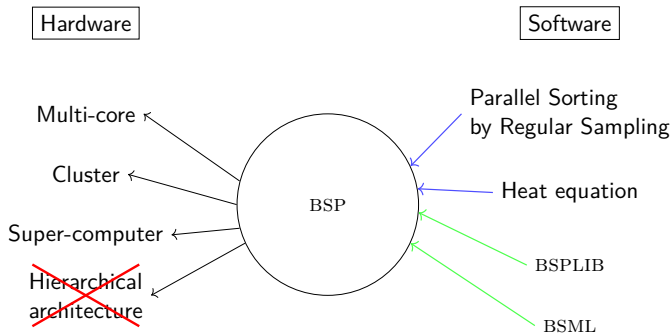
	100_000		500_000		1_000_000	
	MULTI-ML	BSML	MULTI-ML	BSML	MULTI-ML	BSML
8	0.7	1.8	22.4	105.0	125.3	430.7
64	0.3	0.3	1.3	8.7	4.1	56.1

# Table of Contents

- ① Introduction
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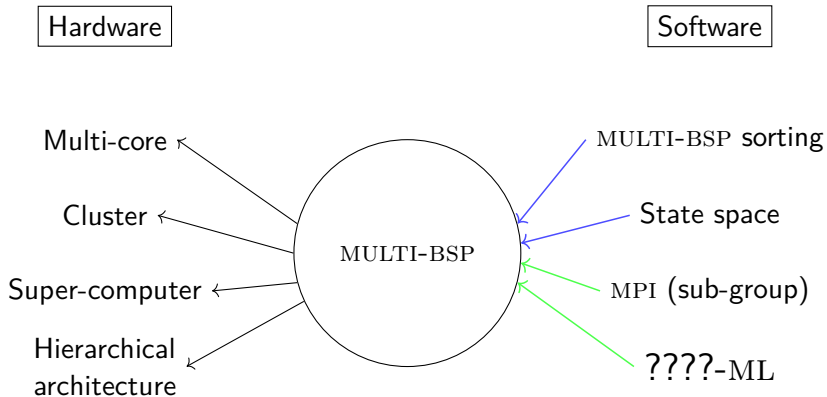
## Before ...

- BSP  $\neq$  Hierarchical architecture
- BSML  $\rightarrow$  BSP à la ML
- No language dedicated to MULTI-BSP

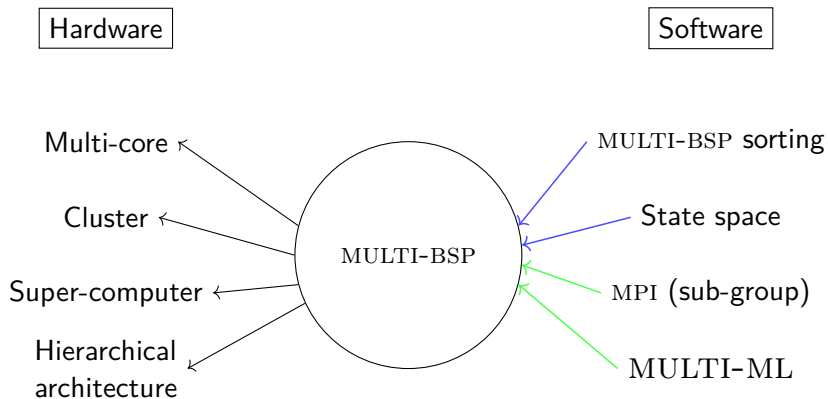


- MULTI-BSP extension of ML
  - Recursive multi-functions `let multi f x = ...`
  - BSMML like code `where node = << f ... >>`
  - Small syntax extension `#, $, at, mkpar, finally, mktree, ...`
- Type system
  - Constraints
  - Effects
- Operational semantics (even for diverging terms)
- Compilation scheme
- $\Rightarrow$  Type safety from programs to abstract machines

Before ...



... Now



## Ongoing work

- Code examples
- Extensions
  - Language
  - Type system

## Future work

- MULTI-ML + GPU  $\Rightarrow$  Hybrid architectures
- Cost analysis
- Certified parallel programming

Thank you for your attention 😊

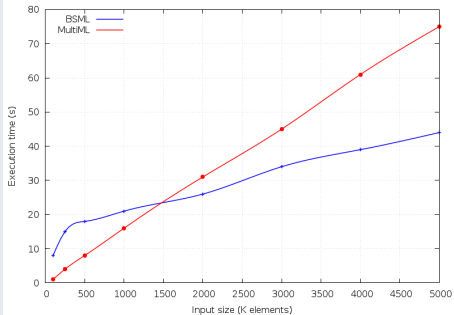
Questions ?



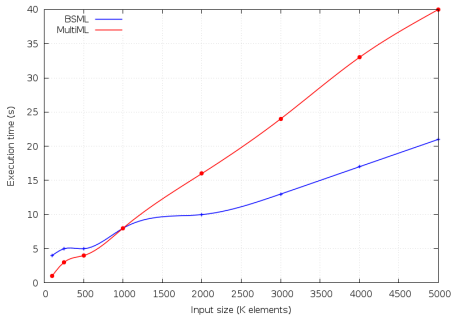
# Fusion Sort

## Fusion Sort on Mirev3 with 32 and 64 threads

Fusion Sort on Mirev3 with 32 th

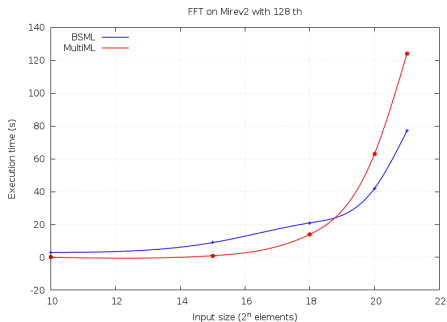
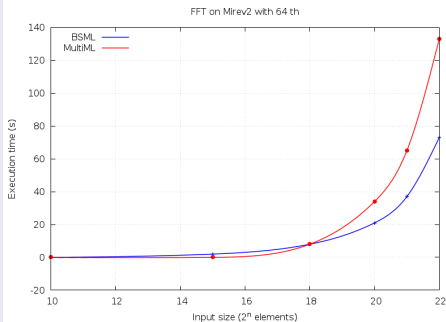


Fusion Sort on Mirev3 with 64 th



# Fast Fourier Transform

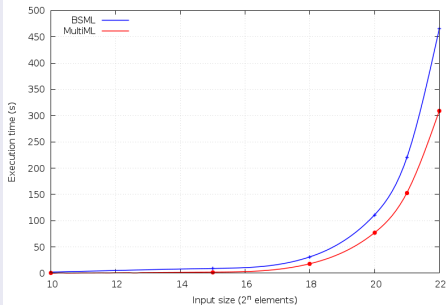
## FFT on Mirev2 (8 machines) with 64 and 128 threads



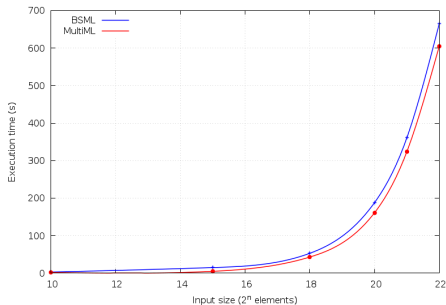
# Fast Fourier Transform

FFT on Mirev2 (6 machines) and Mirev3 (2 machines) with 64 and 128 threads

FFT on Mirev2 and Mirev3 (8 machines) with 64 th



FFT on Mirev2 and Mirev3 (8 machines) with 128 th



## Typing rules

$$\text{LET IN} \frac{\begin{array}{l} \Lambda, \Gamma \vdash e_1 : \tau_{\pi_1}^1 / \varepsilon_1 [c_1] \\ \Lambda, \Gamma; x : \mathbf{Weak}(\tau_{\pi_1}^1, \varepsilon_1) \vdash e_2 : \tau_{\pi_2}^2 / \varepsilon_2 [c_2] \\ c_3 \equiv [\Psi = \mathbf{Propgt}(\varepsilon_1, \varepsilon_2), c_1, c_2] \end{array}}{\Lambda, \Gamma \vdash \mathbf{let } x = e_1 \mathbf{ in } e_2 : \tau_{\pi_2}^2 / \Psi [c_3]}$$

```
<< fun _ -> let x = at t in x >>
```

```
<< let x = at t in fun _ -> x >>
```