

Multi-BSML, une approche à la ML pour la programmation Multi-BSP

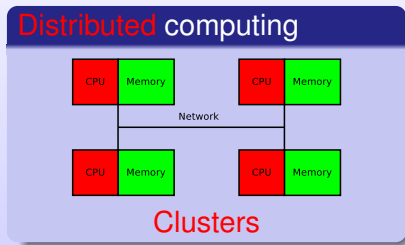
Victor Allombert & Frédéric Gava & Julien Tesson

Laboratory of **A**lgorithms, **C**omplexity and **L**ogic (LACL)
University of Paris-East

Outline

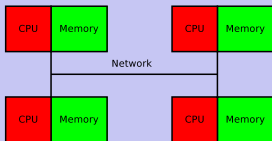
- 1 Introduction
- 2 BSML: Functional BSP Programming
- 3 Multi-BSML : Syntax and semantics
- 4 Conclusion

Parallel Architectures



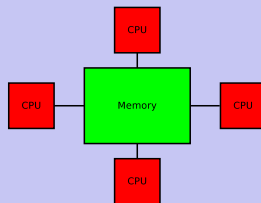
Parallel Architectures

Distributed computing



Clusters

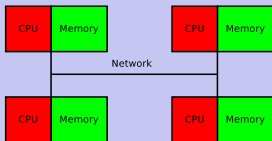
Shared memory



Multi-core

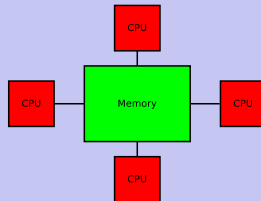
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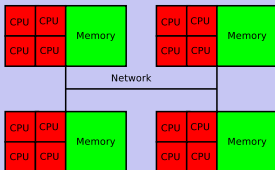
Clusters

Shared memory



Multi-core

Hybrid model



“Think Parallel or Perish”

GPU



Phone



Tablet



Laptop



PC



Cluster



Supercomputer:



(Parallel) Software Errors

Risks

- Over-consumption
- Erroneous results

Typical bugs

Distributed

Shared memory

Deadlocks:

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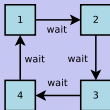
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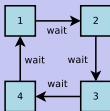
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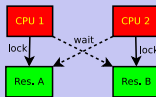
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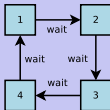
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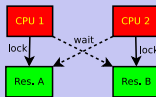
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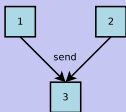
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Race condition:



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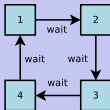
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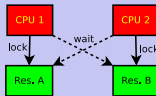
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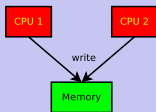
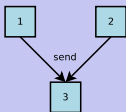
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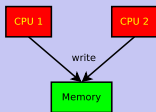
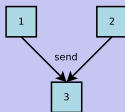
Risks

- Over-consumption
- Erroneous results

Considered solutions

- 1 Well **structured** parallelism;
- 2 Design a **high-level** language for “**hybrid architectures**”
- 3 Software-hardware **bridging model** ⇒ Portability, scalability

Race condition:



Why Structured Parallelism?

Safety, debugging and verification

Reasoning about cost

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Safety, debugging and verification



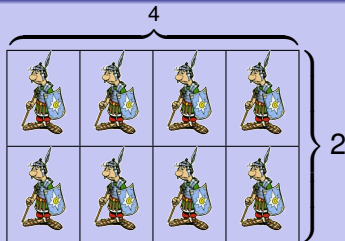
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“Send-receive considered harmful” (Sergei GORLATCH)

- 1 Distributed **extension** of a **functional** language;
- 2 Tools for correctness; (mechanized) Semantics ⇒ **Coq**



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Bridging Model: Bulk Synchronous Parallelism (BSP)

The BSP computer

Defined by:

- **p** pairs **CPU/memory**
- Communication network
- Synchronisation unit
- Super-steps execution

Properties:

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- "Confluent"
- $\forall p \in \mathbb{N}$, \exists a BSP computer with p pairs CPU/memory
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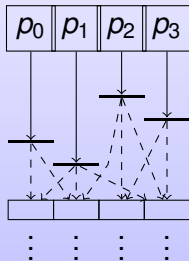
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- "Deadlock-free"
- Predictable performances



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computations

communication
barrier

next super-step

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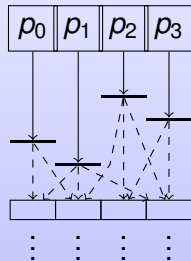
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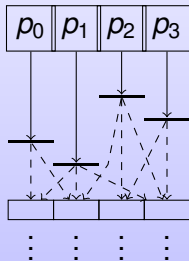
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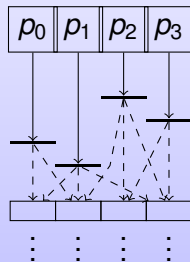
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BSML

- Explicit **BSP** programming with a **functional** approach
- Based upon **ML**; Implemented over **OCaml**
- **Formal semantics** (confluent) → **Coq**

Main idea

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- $(\nu_1, \dots, \nu_n) \circ \text{par} \equiv \nu_i$ on node i
- $\text{primitives} \Rightarrow$ simple semantics

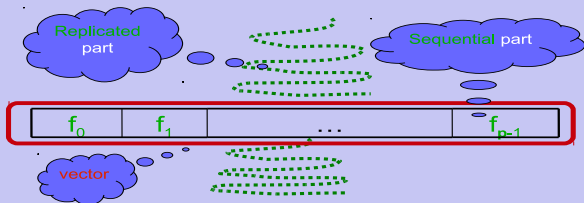
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Parallel data structure \Rightarrow vectors:



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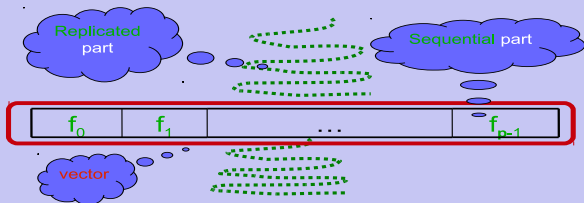
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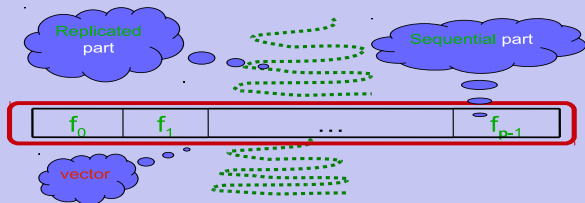
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Asynchronous operations

- `⟨⟨ ... ⟩⟩`: local execution (**vector**)
- `v`: element of a parallel **vector** `v`
- `pid`: id of the processor

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- **proj**: $\langle x_0, \dots, x_{p-1} \rangle \mapsto$

$$\begin{matrix} x_0 \\ \vdots \\ x_{p-1} \end{matrix}$$
- **put**: $\langle f_0, \dots, f_{p-1} \rangle \mapsto$

$$\left\langle \begin{matrix} f_0 0 & & f_0 (p-1) \\ \vdots & & \vdots \\ f_{p-1} 0 & & f_{p-1} (p-1) \end{matrix} \right\rangle$$
- **super**: evaluation of two expressions into super-threads

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Implementation

Modular

- Based on a semantic study:
BSML \equiv $p \times$ ML + 2 BSP instructions (SPMD style)
- Different implementations: TCP/IP, MPI, PUB, ...

Extensions

Inspire:

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- [Inspire: BSP-F# \(L. Gauthier\)](#), [BSP-Python \(K. Insen\)](#)
- [BSP-Perl \(M. J. Snow\)](#), [SnowBSP-F# \(M. J. Snow\)](#)

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- Functional: BSP-Haskell (Q. Miller), Snow/BSP-R (N. Li)

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Example : BSP Sampling Sort

```
(* psrs: int par → 'a list → 'a list *)  
let psrs lvlengths lv =  
  (* super-step 1(a): local sorting *)  
  let locsort = << List.sort compare $lv$ >> in  
  
  (* super-step 1(b): selection of the primary samples *)  
  let regsampl = << extract_n P $lvlengths$ $locsort$ >> in  
  
  (* super-step 2(a): total exchange of the primary samples;*)  
  let glosampl = List.sort compare (proj regsampl) in  
  
  (* super-step 2(b): selection of the secondary samples *)  
  let pivots = extract_n P (P*(P-1)) glosampl in  
  
  (* super-step 2(c) : building the communicated lists of values *)  
  let comm = << slice_p $locsort$ pivots >> in  
  
  (* super-step 3: sended them and merging of the received values *)  
  let recv = put << List.nth $comm$ >> in  
  << p_merge P (List.map $recv$ procs_list) >>
```

Advantages and Drawbacks

Advantages

- Easy to learn
- “All” OCaml codes can be used
- Easy to get a BSML code from a BSP algorithm

Drawbacks

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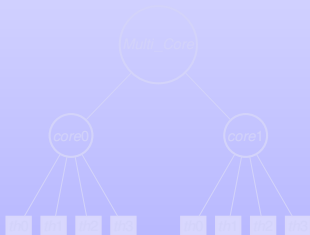
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Multi-BSP Model (1)

What is Multi-BSP? (Valiant)

- 1 A **tree** structure with **nested** components
- 2 Where **nodes** have a storage capacity
- 3 And **leaf** are homogenous processors

Multi-BSP



BSP

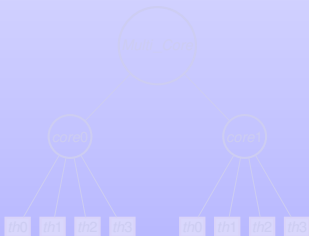


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BSP

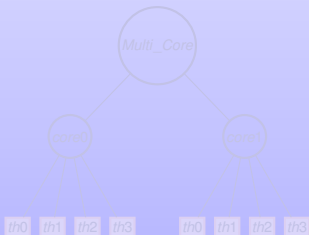


Multi-BSP Model (1)

What is Multi-BSP? (Valiant)

- 1 A **tree** structure with **nested** components
- 2 Where **nodes** have a storage capacity
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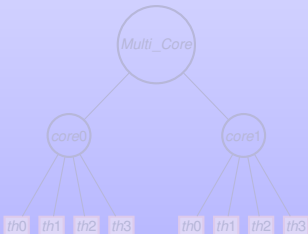


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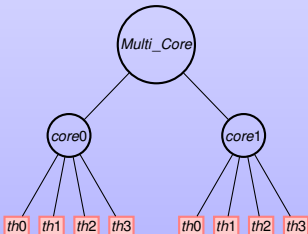


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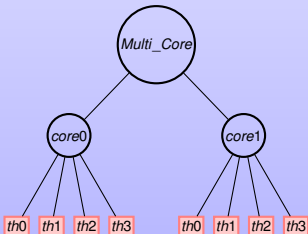


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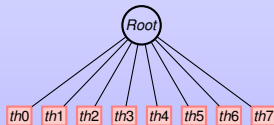
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Cost model

A d depth tree is specified by $4 \times d$ parameters:

- p : Number of sub-components
- m : Available memory at a level
- g : Bandwidth with the upper level
- L : Synchronisation

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Example: 16 quad-chips with octo-cores

- Level 4 ($p = 16, g = \infty, L = 1000, m = 16Tb$) (RAM/IO)
- Level 3 ($p = 4, g = 150, L = 100, m = 64Gb$) (RAM)
- Level 2 ($p = 8, g = 5, L = 10, m = 2Mb$) (L2 cache)
- Level 1 ($p = 1, g = 1, L = 1, m = 8Kb$) (L1 cache)

Multi-BSP Model (3)

Execution model

At a level i , a **super-step** is:

- Each **component** at level $i - 1$ does its own **super-steps**
- Then each **copies** some data to the memory at level i
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Advantages and drawbacks

- Implicit **subgroup** synchronisation
- **Recursive** decomposition of problems
- **Harder** to **design/cost** some algorithms

Multi-BSML Language (1)

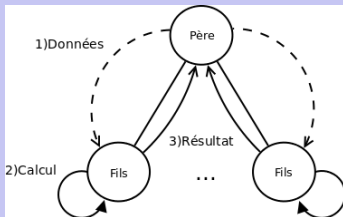
Syntactic construction

```
let multi f [args] =  
  let cst = CodeOCaml  
  where node [args] = CodeBSML ...  
    << f args >>  
    ... CodeBSML  
  where leaf [args] = CodeOCaml  
in f ...
```


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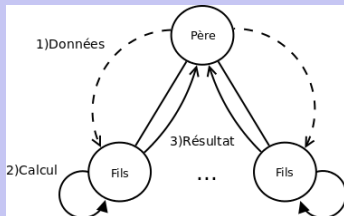
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Limitations and differences

- Nodes are **implicit** computation units
- **Horizontal** communications between level components
- **Garbage collector** ⇒ no L1, L2 caches.

Multi-BSML Language (2)

Semantics of multi

- BSML code to **distribute** values
- `⟨⟨ ... ⟩⟩` and **proj**; **level** changing
- Mutual **recursive** functions of standard OCaml values
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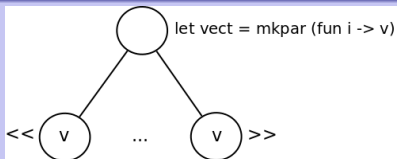
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Copy memory values and distribution of values

- **let** $x = 1$ **in** $\ll \#x\# + 1 \gg$
- **mkpar** ($\text{fun } i \rightarrow e$)
 $\mapsto \langle v_0, \dots, v_{p-1} \rangle$
 where $(e \ i) \mapsto v_i$



Example : Sum Of The Elements Of A List

```
let multi sum_list l =  
  
  where node l =  
    let v = mkpar (fun i → split i l) in  
      sumSeq (flatten << sum_list $v$ >>) (* flatten uses a proj *)  
            (* sumSeq is List.fold_left *)  
  
    where leaf l = sumSeq l  
  
in ... (sum_list lst) ...
```

Multi With Tree Construction

Goals

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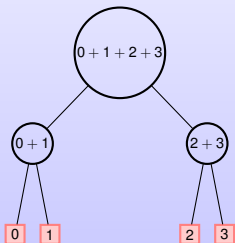
Extension

Two new keywords:

- **finally**; **pushes** up a value and **keeps** a value
- **where default**; **keeps** a value even if the recursive calls generates **partial** trees; Optional if the language allows to raise exceptions

Example

Keep the intermediate results of the sum



```
let multi sum_list l =
```

```
  where node l =
```

```
    let v = mkpar (fun i → split i l) in
```

```
    let s = sumSeq (flatten << sum_list $$ >>) in
```

```
    finally ~up:s ~keep:s
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```
  where leaf l =
```

```
    let s = sumSeq l in
```

```
    finally ~up:s ~keep:s
```

```
  where default = 0 (* not used *)
```


Implementation

Sequential (currently test phase)

For **debugging** and **toplevel**

- **tree** structure of data
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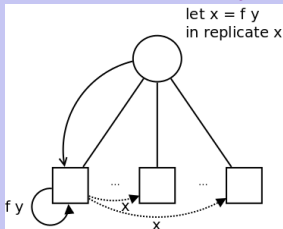
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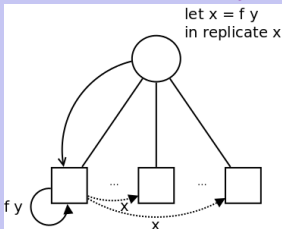
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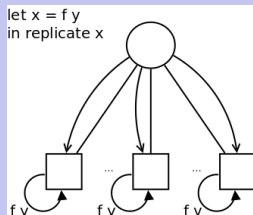
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Why ?

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The multi skeleton

mktree : 'a tree → 'b → 'e tree → down → leaf → up → control → ('c*'e tree)
where

down: 'a → 'b → 'b par

leaf: 'e → 'a → 'b → ('c * 'e)

up: 'd par → 'e → 'a → 'b → ('c * 'e)

control: 'c par → 'e → 'a → 'b → UP **of** ('d par * 'e) | DOWN **of** ('b * 'e)

Outline

- 1 Introduction
- 2 BSML: Functional BSP Programming
- 3 Multi-BSML : Syntax and semantics
- 4 Conclusion**

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- Examples and benchmarks
- Type system for a subpart of OCaml again

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