



LABORATOIRE ESTAS  
ÉVALUATION DES SYSTÈMES  
DE TRANSPORTS AUTOMATISÉS  
ET DE LEUR SÉCURITÉ

# Formal alignment of high-level architecture models with requirements models

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# Outline of the presentation

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- Context of the work
- HLA modelling and verification approach
- SysML/KAOS approach
- Graphical alignment links
- Formalization of graphical alignment links
- Conclusion

# Context

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- **Autonomous freight train project:** a project of the French IRT Railenium (Technological Research Institute), involving industrial and academic partners for developing Rail Research and Innovation.
- In the project, complex systems are seen as an **interplay** of heterogeneous sub-systems, generally **critical**, in particular their development process is most often **challenging** since it could be difficult to verify that stakeholders needs are **satisfied**.
- **High-level architecture** (HLA) of these systems are represented as an **interconnected hierarchy** of their sub-systems
- **Requirements traceability** is a **crucial** element of any especially for the design of critical complex systems

# Problem statement and motivations

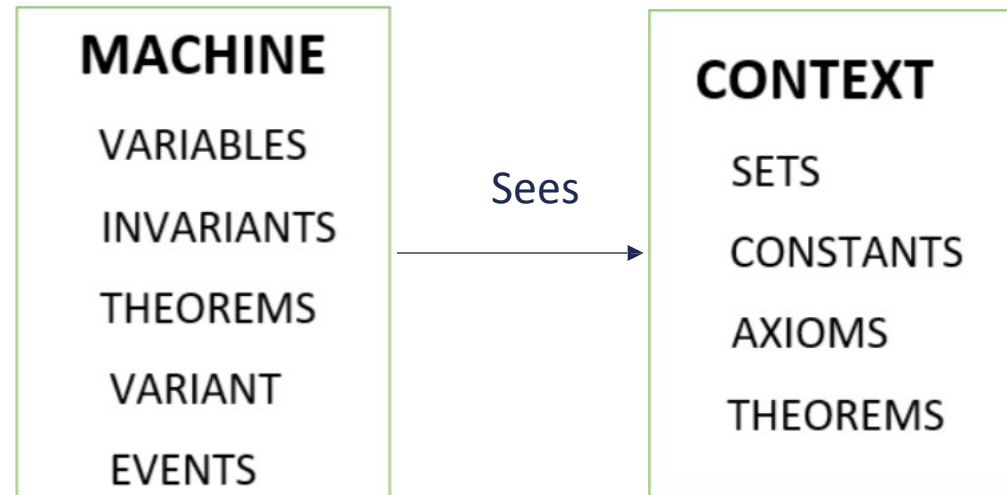
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- High-level architecture (HLA) models must be aligned with requirements models.
  - The need of a graphical alignment links between HLA models and requirements models for critical systems.
- Critical complex systems require **formal** and **rigorous** reasoning.
  - The need of a formalization of these alignment links.

**Our objective: Defining graphical and formal alignments to be validated by experts of various domains (railways systems)**

# Event-B

- A **formal method** based on set theory and first order logic
- An Event-B model is composed of a set of **contexts** and **machines**



*Event E = SELECT G(v) THEN S(v) END*

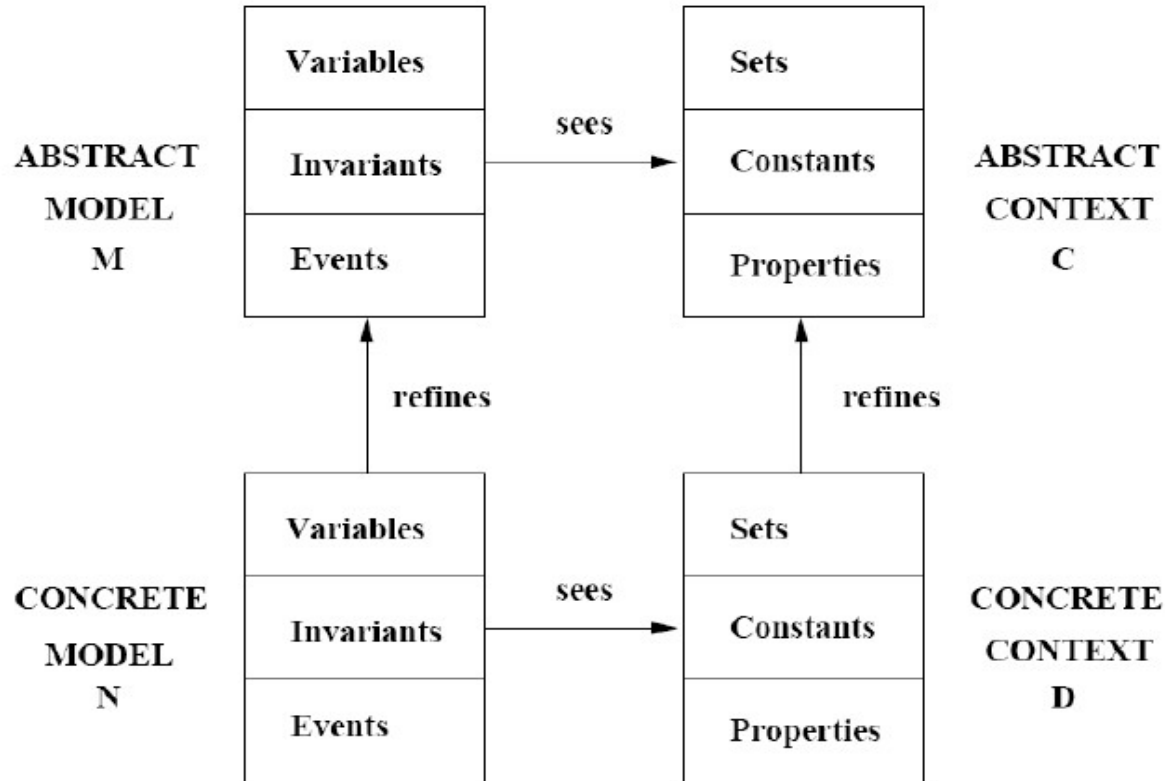
with

**G(v)** : guard

**S(v)** : substitution

**v** : state variables and local variables

# Event-B refinement process



- **Semantics** of models and refinements given by **proof obligations**
- **Supported by industrial tools** (AtelierB, ProB, Rodin platform ...)

# HLA modelling

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- Providing an **automatic translation** from **SysML** diagrams to **Event-B** specifications
- **Extending SysML** with the **refinement** and **decomposition** mechanisms of Event-B to facilitate a **step-by-step design** for mastering complexity

# The methodology for HLA modelling

## High-level architecture

Package  
Diagram

BDD  
Diagram

State-machine  
Diagram

Sequence  
Diagram

SysML refinement &  
decomposition  
mechanisms

Model to Model  
transformation

Event-B  
Model

Theorem  
Provers

Formal  
Verification/  
Validation

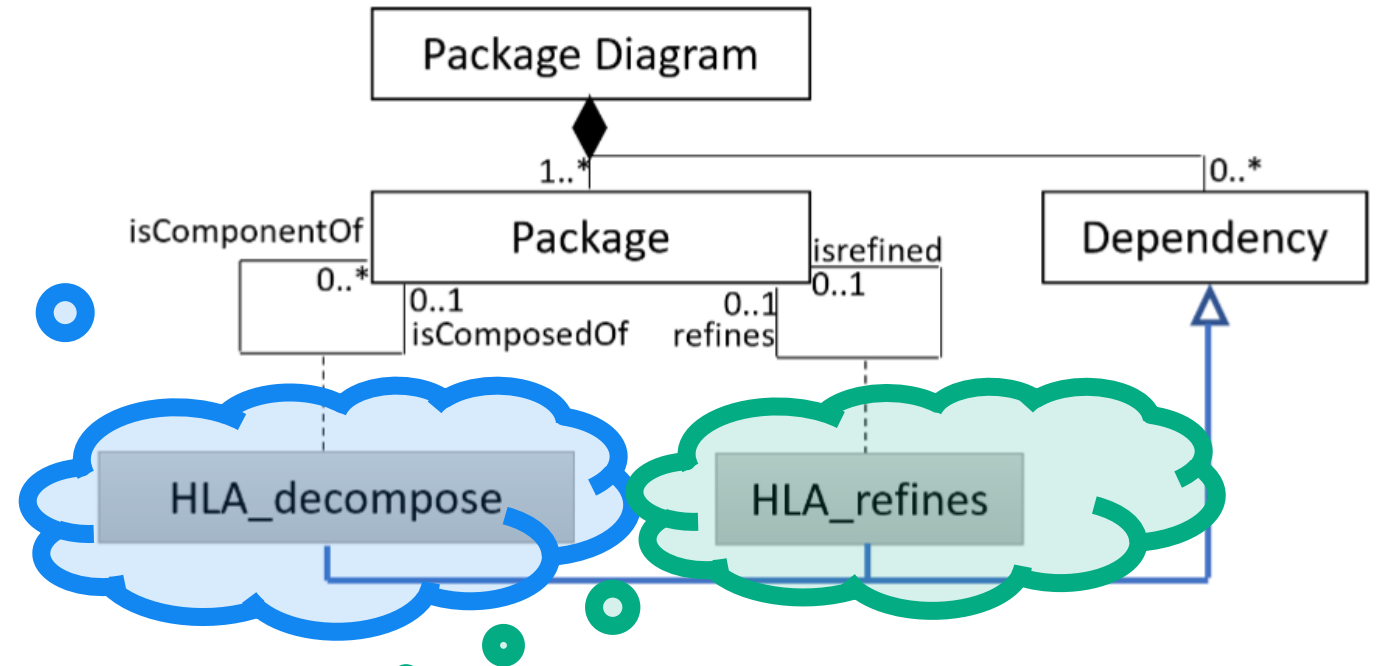
Animators

Model  
Checkers



# SysML package diagram extensions with refinement and decomposition mechanisms

**HLA\_decompose**: allows to decomposed a **package** modeling a **system** into a set of **packages** modeling each of its **sub-systems**

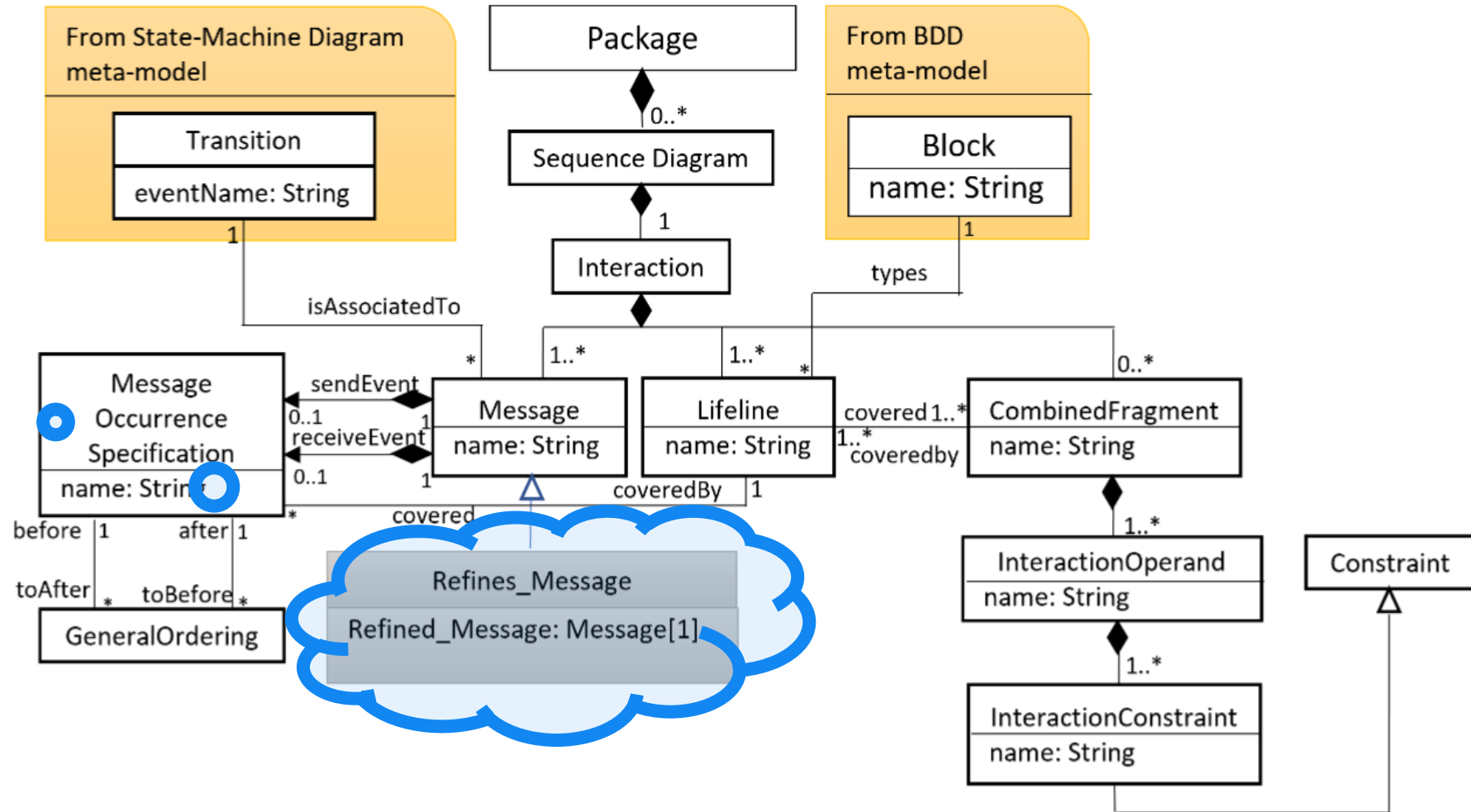


**HLA\_refines**: defined between two packages. The **refined package** contains the modeling elements of a **system**. The **refining package** contains the modeling elements of its **sub-systems to detail the behavior** of the parent package

# SysML sequence diagram extension with refinement

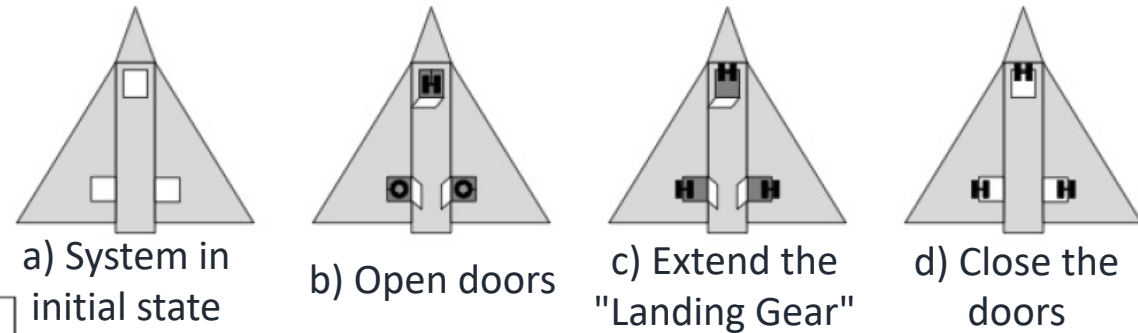
## SysML sequence diagram extension:

A message of a refining package is a refinement of a message of the refined package.

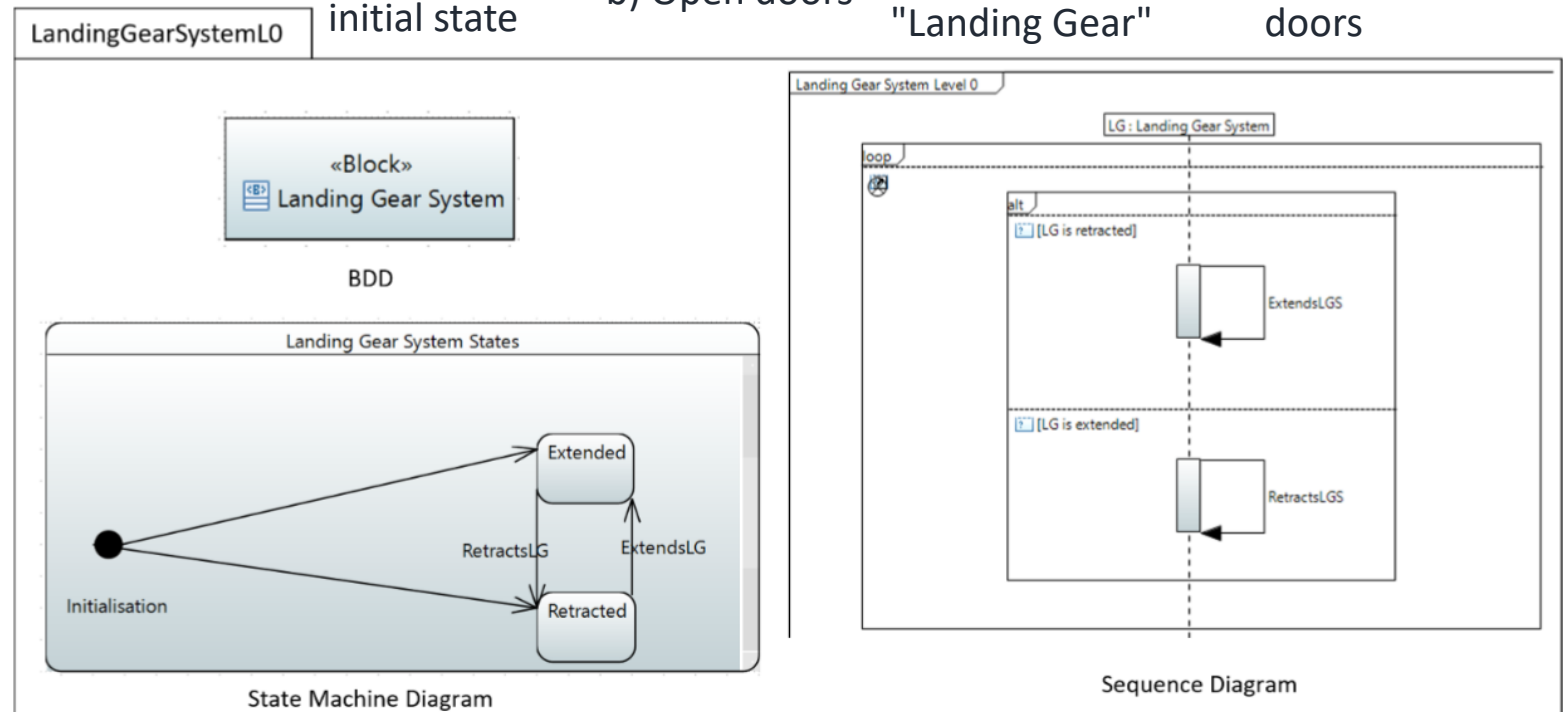


# Illustration of the SysML extensions

## Landing Gear System case study

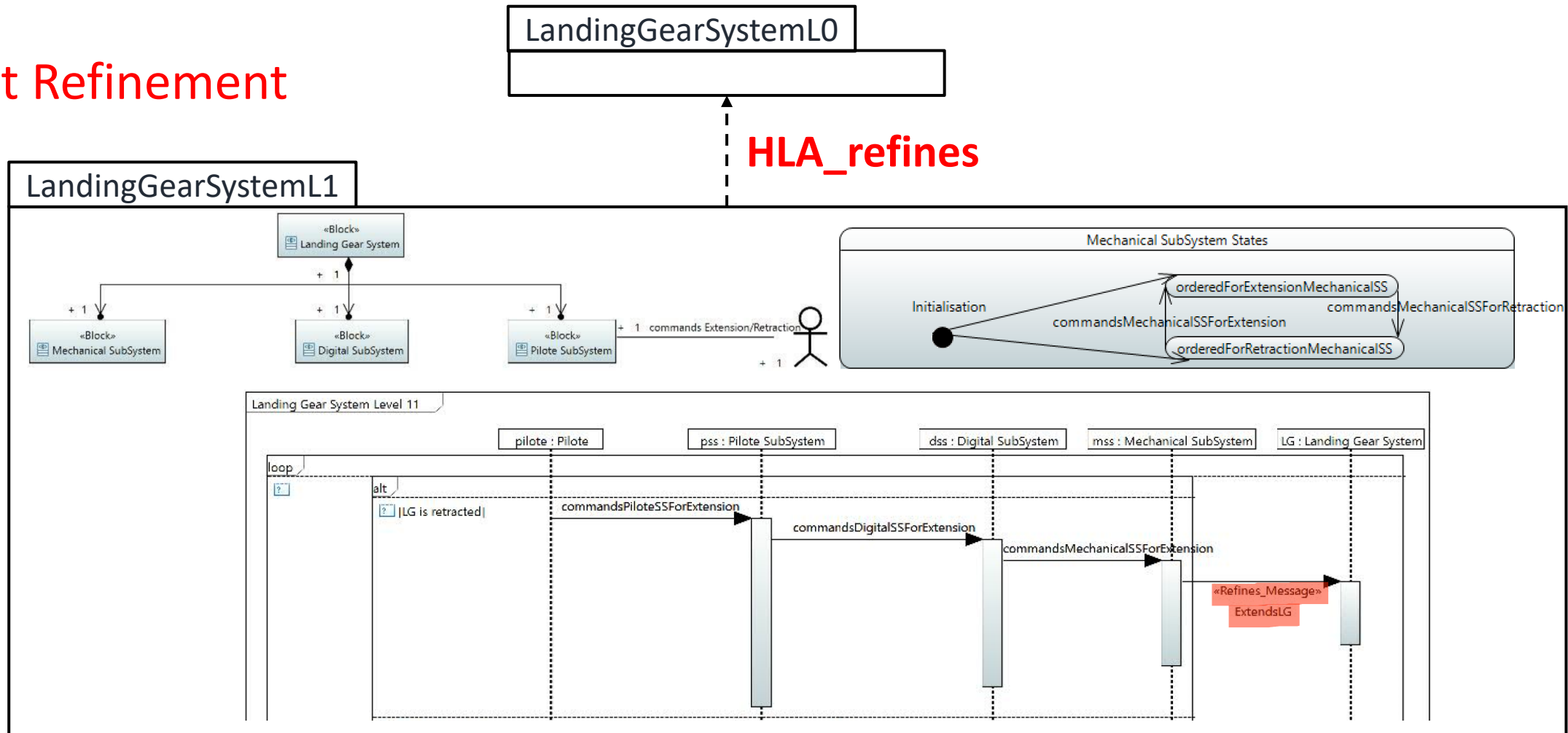


## Abstract Model



# Illustration of the SysML extensions

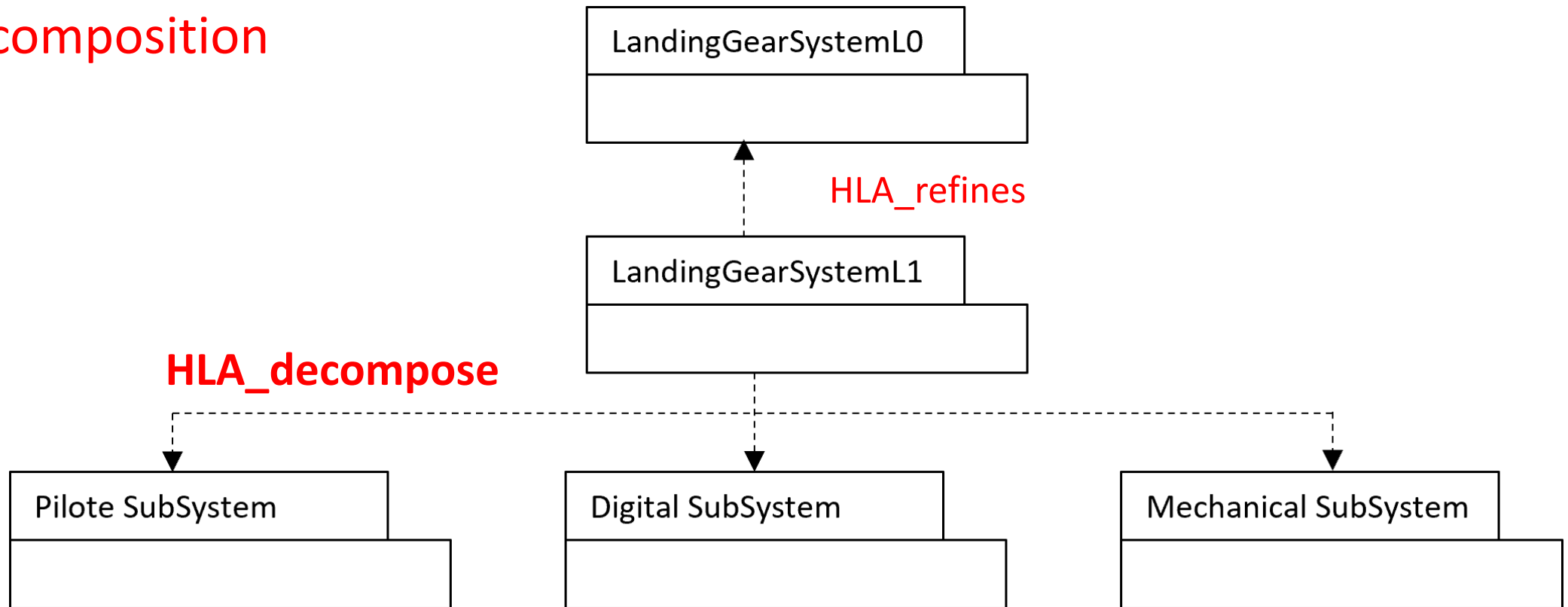
## First Refinement



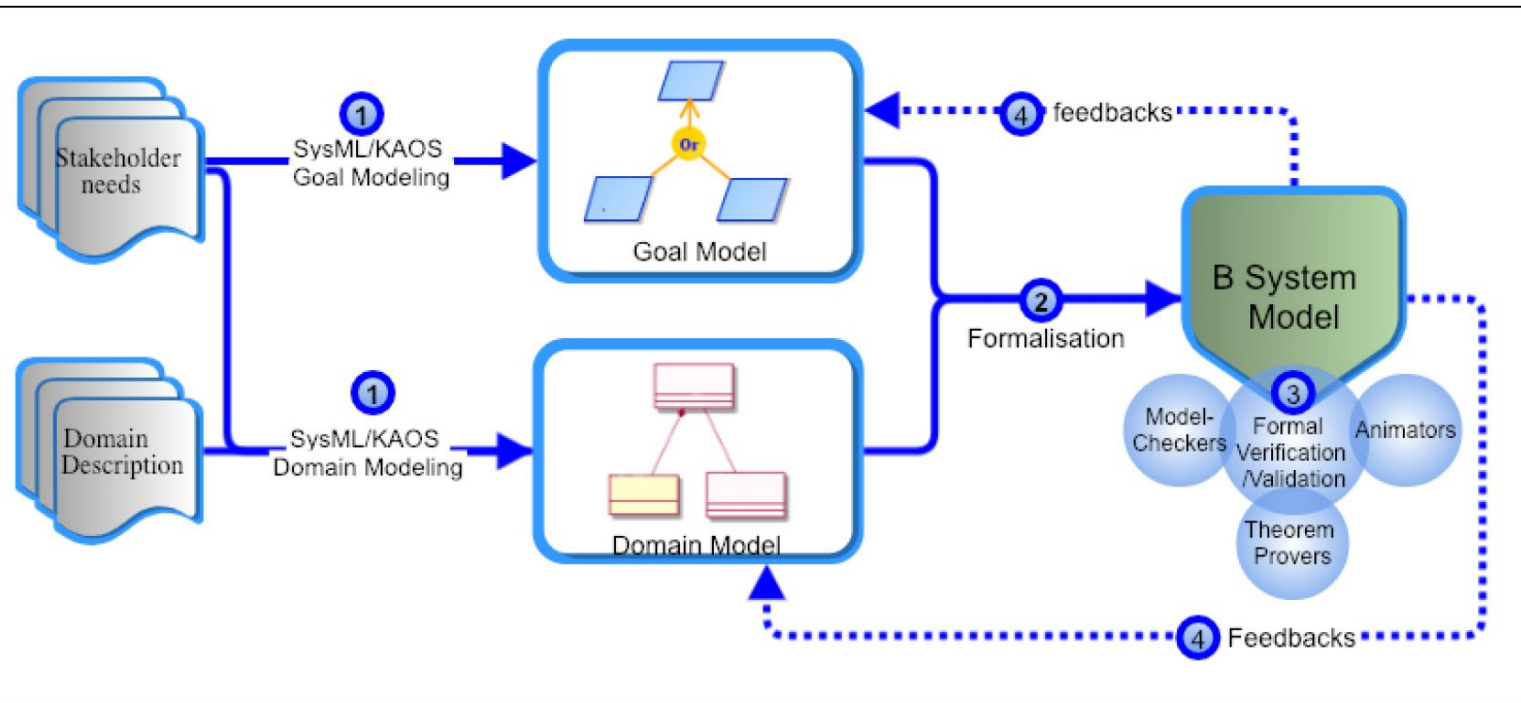
# Illustration of the SysML extensions

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## First Decomposition



# Modelling requirements: the SysML/KAOS approach



```

SYSTEM TrainControllerL3_CONT
SETS DESTINATIONS; TRAIN_ENGINE_STATES; TRAIN_STATES;
CONSTANTS progressing, moving, stopped, ...
PROPERTIES

...
TRAIN_STATES = {progressing, moving, stopped}
END

EXTRACT FROM THE EVENT-B SPECIFICATION OF SYSML/KAOS REQUIREMENTS MODEL Level 1
    
```

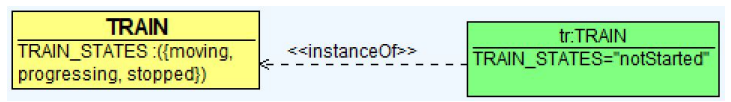
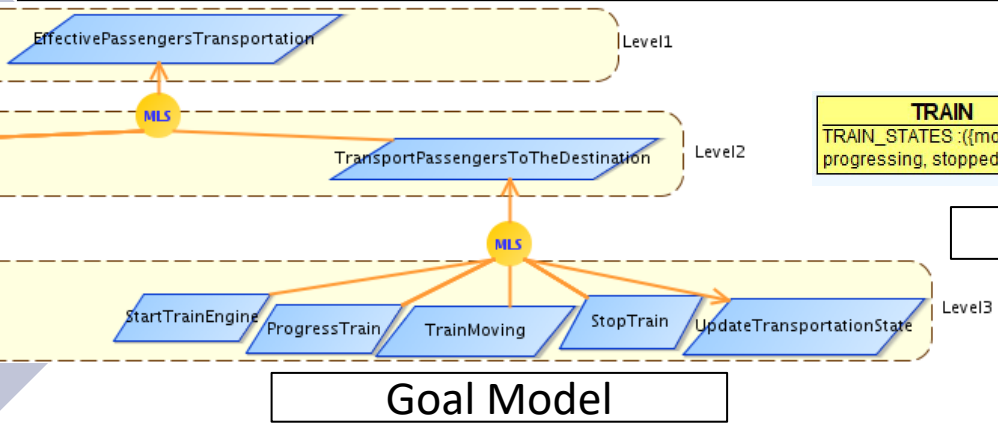
```

REFINEMENT TrainControllerL3
REFINES TrainControllerL2
SEES TrainControllerL1 CONT, TrainControllerL2 CONT, TrainControllerL3 CONT
VARIABLES trainState, ...
INVARIANTS trainState ∈ TRAIN → TRAIN_STATES ∧ ...
INITIALISATION trainState :∈ TRAIN → {stopped} || ...
EVENTS

...
ProgressTrain ref milestone TransportPassengersToTheDestination =
SELECT trainState(tr) = stopped THEN trainState(tr) := progressing
END;

...
StopTrain ref milestone TransportPassengersToTheDestination =
SELECT trainState(tr) = moving THEN
trainState(tr) := stopped END
END

EXTRACT FROM THE EVENT-B SPECIFICATION OF SYSML/KAOS REQUIREMENTS MODEL Level 2
    
```



FOTSO, Steve Jeffrey Tueno, FRAPPIER, Marc, LALEAU, Regine, et al. Back propagating B system updates on SysML/KAOS domain models. In : 2018 23rd International Conference on Engineering of Complex Computer Systems (ICECCS). IEEE, 2018. p. 160-169.

# Aligning HLA with requirements

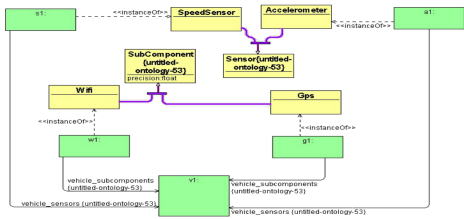
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- Providing **graphical alignment** links between requirements models and HLA models
- Providing an **automatic translation** from **graphical alignment links** to **Event-B** specifications

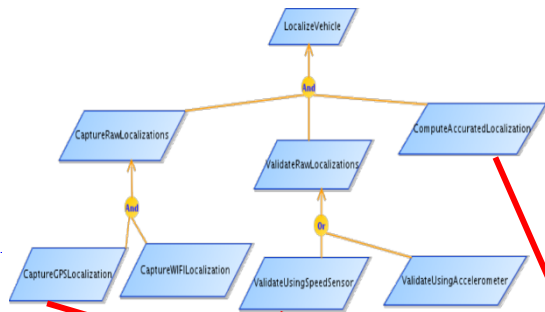
# Aligning HLA with requirements

## 1. SysML/KAOS Modeling

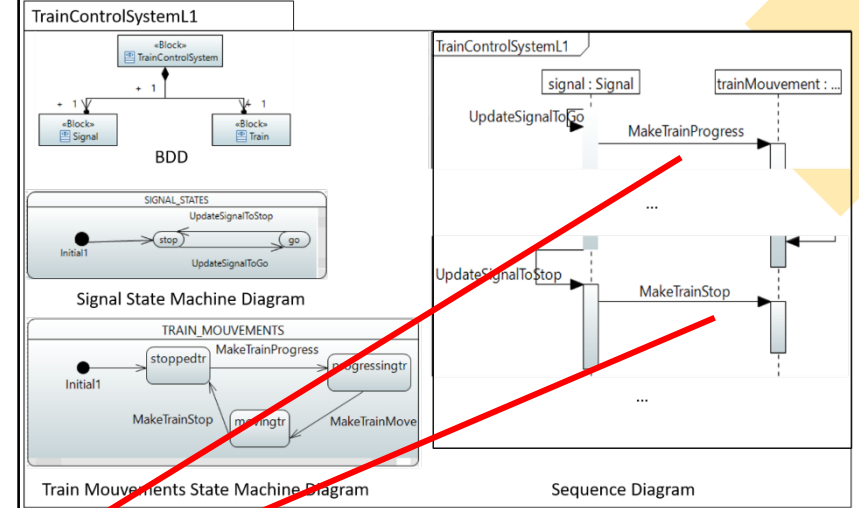
### Domain Model



### Goal Model



## 2. SysML HLA Modeling



Graphical alignment links between requirements models and HLA models

### 3. Alignment

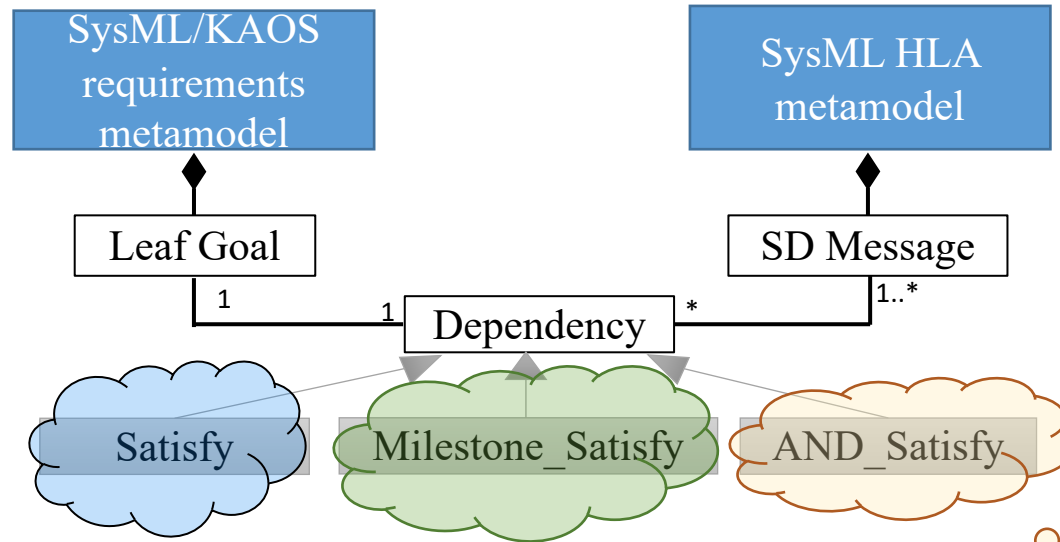
Automatic translation from graphical alignment links to Event-B specifications

Event-B Specification



# Alignment links

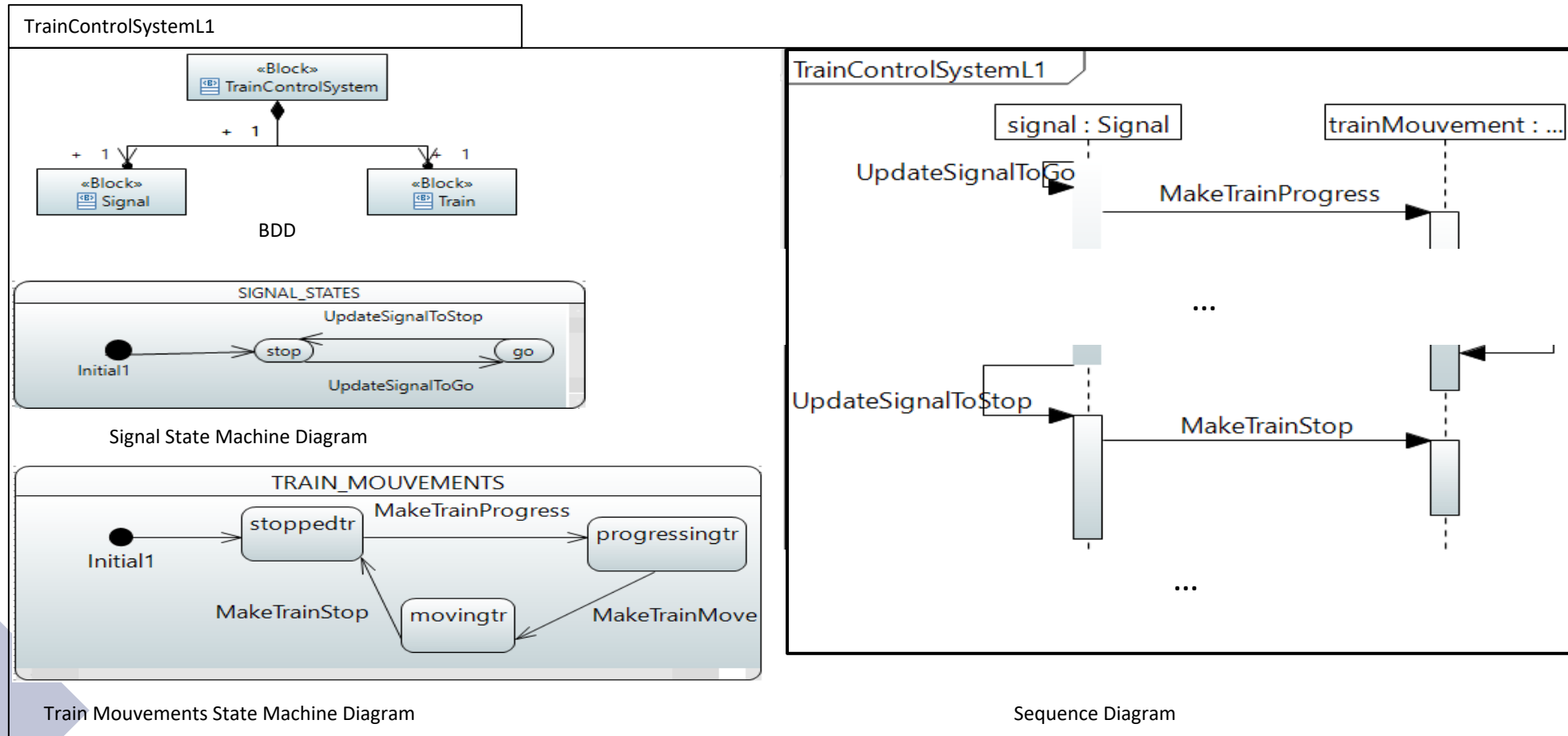
**Satisfy**: allows to define an alignment link when a message can satisfy a goal.



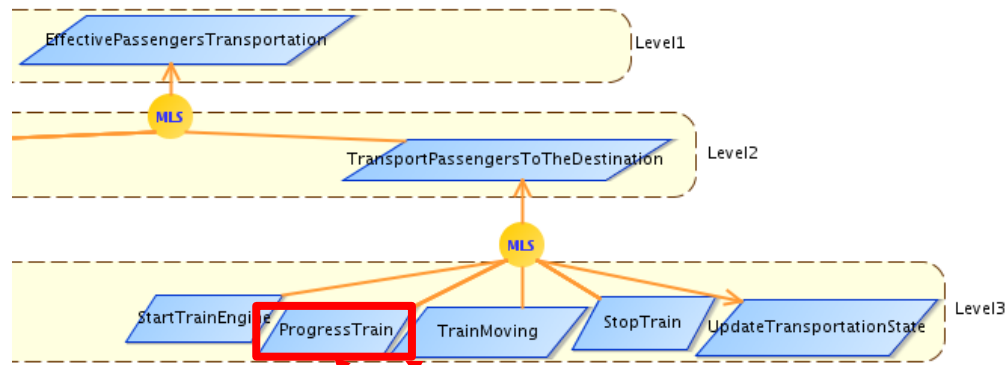
**Milestone\_Satisfy**: is defined when a sequence execution of a set of messages in a specific order is necessary to satisfy a goal.

**AND\_Satisfy**: is defined when a goal is satisfied by a set of messages, i.e. the execution of all of them, in any order, is necessary to satisfy the goal.

# Illustration with the Train control system case study: HLA modelling

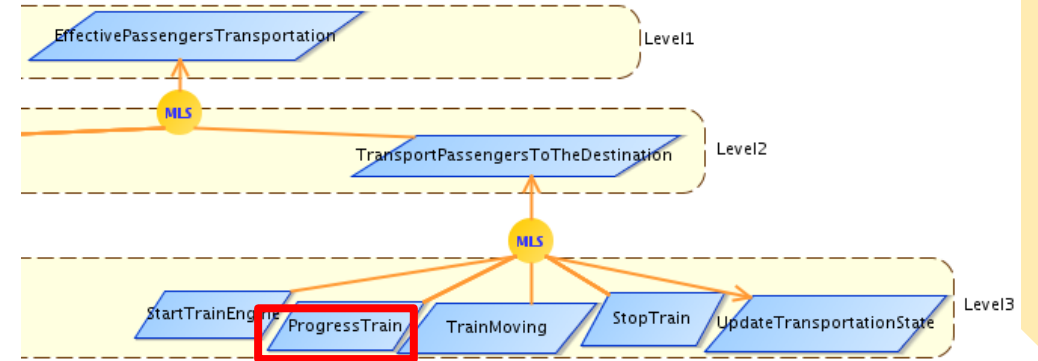


# Illustration of the alignment links



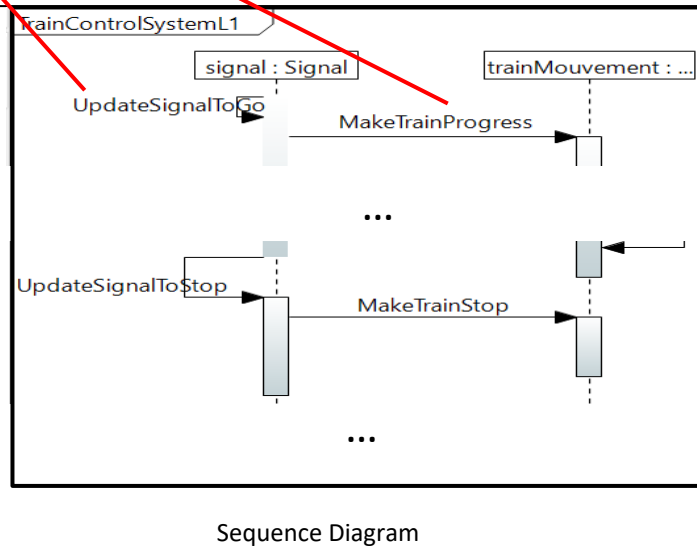
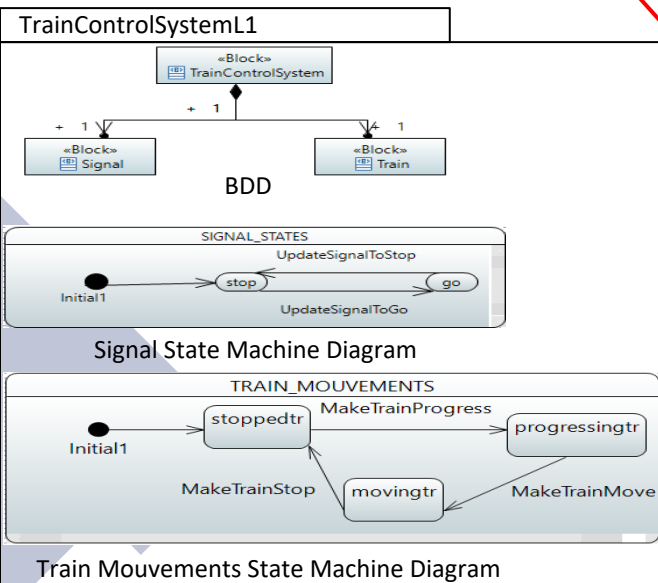
1.« Milestone\_Satisfy »

2.« Milestone\_Satisfy »



1.« Milestone\_Satisfy »

2.« Milestone\_Satisfy »

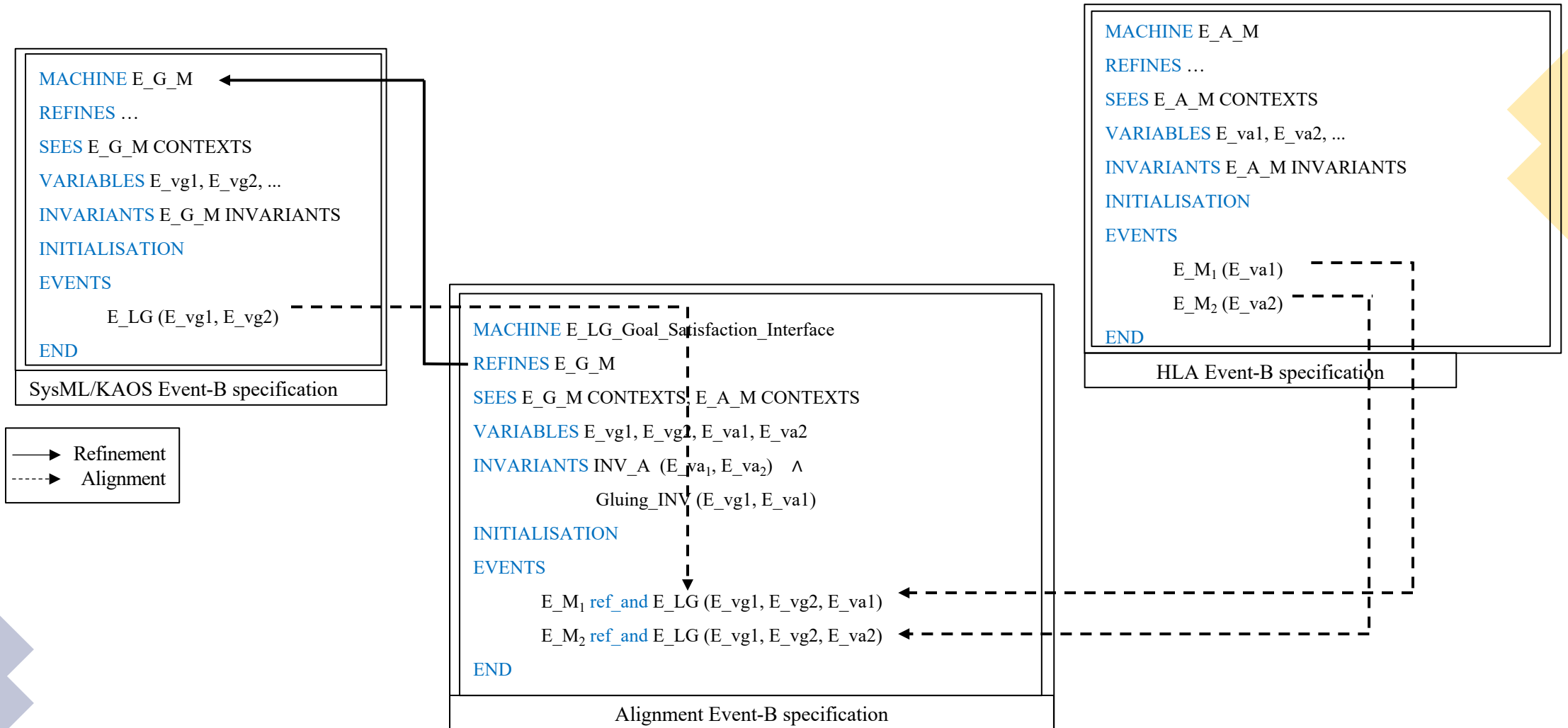


# Formalization of graphical alignment links

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- A refinement relationship between Event-B events from message and leaf goal,
  - × The Event-B refinement semantics do not match our alignment semantics,
  - × Messages that satisfy a leaf goal can belong to distinct Event-B machines,
- The formalization of SysML/KAOS models and SysML HLA models is performed in Event-B,
  - A new Event-B machine is built for each alignment link,
  - New sets of refinement proof obligations are specified, one for each type of alignment.

# EVENT-B architecture of the proposed alignment



# Formalization of graphical alignment links: some rules

		Source concepts		Target concepts	
Rule	Translation of	Element	Constraint	Element	Constraint
1	Leaf goal to satisfy	LG E_LG	LG is the leaf goal E_LG is the event related to LG E_G_M is the Event-B machine that contains E_LG	E_LG_Goal_Satisfaction_Interface	E_LG_Goal_Satisfaction_Interface ∈ <b>MACHINE</b> ; E_LG_Goal_Satisfaction_Interface <b>REFINES</b> E_G_M; E_LG_Goal_Satisfaction_Interface <b>SEES</b> E_G_M CONTEXTS;
2	Variables involved in E_LG	E_vg <sub>i</sub> , i ∈ [1..n]	E_vg <sub>i</sub> are the variables of E_G_M involved in E_LG	E_vg <sub>i</sub> , i ∈ [1..n]	E_vg <sub>i</sub> ∈ <b>VARIABLES</b>
3	Messages responsible for the satisfaction of the leaf goal LG	M <sub>j</sub> E_M <sub>j</sub> j ∈ [1..p]	M <sub>1</sub> , ... M <sub>p</sub> are messages E_M <sub>j</sub> is the event related to message M <sub>j</sub> ; E_A_M <sub>j</sub> is the Event-B machine that contains E_M <sub>j</sub>	E_M <sub>j</sub> j ∈ [1..p]	E_M <sub>j</sub> ∈ EVENTS E_LG_Goal_Satisfaction_Interface <b>SEES</b> E_A_M <sub>j</sub> CONTEXTS
4	Variables involved in E_M <sub>j</sub> events	E_va <sub>j,k</sub> j ∈ [1..p] k ∈ [1..q]	E_va <sub>j,k</sub> are the variables involved in E_M <sub>j</sub> INV_A_M <sub>j</sub> (E_va <sub>j,1</sub> , ..., E_va <sub>j,q</sub> ) is the part of E_A_M <sub>j</sub> invariant related to the E_va <sub>j,k</sub> variables	E_va <sub>j,k</sub> , j ∈ [1..p] k ∈ [1..q]	E_va <sub>j,k</sub> ∈ <b>VARIABLES</b> INV_A_M <sub>j</sub> (E_va <sub>j,1</sub> , ..., E_va <sub>j,q</sub> ) ∈ <b>INVARIANTS</b>

# Formalization of graphical alignment links: Proof obligations

- Gluing invariant are constructed in the machine  $E\_LG\_Goal\_Satisfaction\_Interface$  to links variables of the HLA EVENT-B machines  $E\_A\_M_j$  to variables of the SYSML/KAOS EVENT-B machine  $E\_G\_M$ .
- **Alignment proof obligations:**

Let LG be a leaf goal and M1, M2 two messages. Let  $E\_LG$  be the event associated to LG and  $E\_M_1, E\_M_2$  the two events associated to M1 and M2. Each event E is of the form:

$$E = \mathbf{SELECT} E\_Guard \mathbf{THEN} E\_Post.$$

- **Satisfy** relationship. Assume that LG is satisfied by M1, then:

$$E\_M_1 \mathbf{ref} E\_LG$$

where **ref** is the standard EVENT-B refinement.

This proof obligation ensures that the execution of  $E\_M_1$  implies the satisfaction of  $E\_LG$ .

# Formalization of graphical alignment links: And\_Satisfy alignment

- **And\_Satisfy** relationship. Assume that LG is satisfied by M1 and M2, then:

$$E\_M_1 \text{ ref\_and } E\_LG$$
$$E\_M_2 \text{ ref\_and } E\_LG$$

- New proof obligations are generated:

$$E\_M_1\_Guard \Rightarrow E\_LG\_Guard$$
$$E\_M_2\_Guard \Rightarrow E\_LG\_Guard$$
$$(E\_M_1\_Post \wedge E\_M_2\_Post) \Rightarrow E\_LG\_Post$$

- These proof obligations ensure firstly that  $E\_M_1\_Guard$  and  $E\_M_2\_Guard$  should never contradict  $E\_LG\_Guard$  and secondly the execution of  $E\_M_1$  and  $E\_M_2$  without any specific order implies the satisfaction of  $E\_LG$ .



# Formalization of graphical alignment links: Milestone\_Satisfy alignment

- **Milestone\_Satisfy** relationship. Assume that LG is satisfied by the sequential execution of M1 and M2, then:

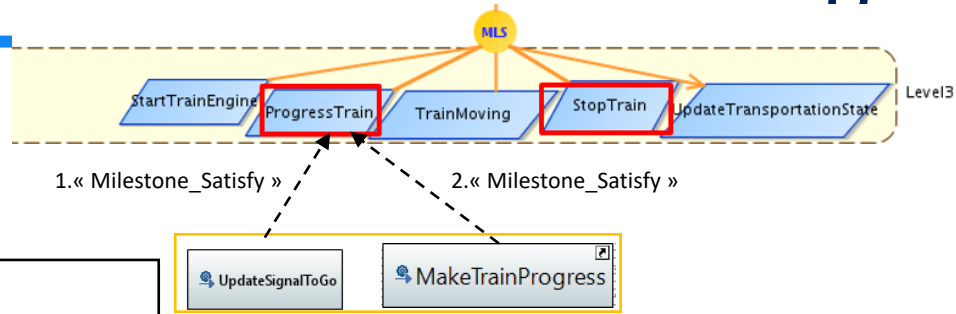
$$E\_M_1 \text{ ref\_milestone } E\_LG$$
$$E\_M_2 \text{ ref\_milestone } E\_LG$$

- New proof obligations are generated:

$$E\_M_1\_Guard \Rightarrow E\_LG\_Guard$$
$$E\_M_1\_Post \Rightarrow E\_M_2\_Guard$$
$$E\_M_2\_Post \Rightarrow E\_LG\_Post$$

- These proof obligations ensure firstly that  $E\_M_1\_Guard$  should never contradict  $E\_LG\_Guard$ . Secondly the scheduling constraint should be respected with  $E\_M_1\_Post$  implies  $E\_M_2\_Guard$  and finally the execution of  $E\_M_1$  followed by the execution of  $E\_M_2$  implies the satisfaction of  $E\_LG$

# Illustration of the formalization the alignment links



```

REFINEMENT TrainControllerL3
Refines TrainControllerL2
SEES TrainControllerL1_CONT, TrainControllerL2_CONT, TrainControllerL3_CONT
VARIABLES trainState, ...
...
EVENTS
ProgressTrain ref_milestone TransportPassengersToTheDestination =
SELECT trainState (tr) = stopped THEN trainState (tr) := progressing
END ;
...
END
    
```

EXTRACT FROM THE EVENT-B SPECIFICATION OF SYMML/KAOS  
REQUIREMENTS MODEL Level 2

```

REFINEMENT TrainControlSystemL1
REFINES TrainControlSystemL0
SEES TrainControlSystemL1_CONT, TrainControlSystemL0_CONT
VARIABLES signalState, trainMouvementState
...
EVENTS
UpdateSignalToGo =
SELECT signalState = stop  $\wedge$  trainMouvementState ( train )= stoppedtr THEN signalState := go END ;

MakeTrainProgress =
SELECT signalState = go  $\wedge$  trainMouvementState ( train )= stoppedtr THEN
trainMouvementState (train) := progressingtr END ;
...
END
    
```

EXTRACT FROM THE EVENT-B SPECIFICATION OF HLA

```

REFINEMENT ProgressTrain Goal Satisfaction Interface
REFINES TrainControllerL3
SEES TrainControllerL1 CONT, TrainControllerL2 CONT, TrainControllerL3 CONT, TrainControlSystemL1 CONT
VARIABLES ..., trainState, signalState, trainMouvementState
INVARIANTS
signalState  $\in$  SIGNAL STATES  $\wedge$  trainMouvementState  $\in$  TRAINS  $\rightarrow$  TRAIN MOUVEMENTS
 $\wedge$  (trainMouvementState[TRAINS] = {stoppedtr}  $\Rightarrow$  trainState[TRAIN] = {stopped}) \\gluing invariant
 $\wedge$  (trainMouvementState[TRAINS] = {progressingtr}  $\Rightarrow$  trainState[TRAIN] = {progressing}) \\gluing invariant
 $\wedge$  (trainMouvementState[TRAINS] = {movingtr}  $\Rightarrow$  trainState[TRAIN] = {moving}) \\gluing invariant
INITIALISATION
...
signalState := {stop} ||
trainState, trainMouvementState : ((trainState  $\in$  TRAIN  $\rightarrow$  {stopped})  $\wedge$  (trainMouvementState := TRAINS  $\rightarrow$ 
{stoppedtr}))
 $\wedge$  (trainMouvementState[TRAINS] = {stoppedtr}  $\Rightarrow$  trainState[TRAIN] = {stopped})
 $\wedge$  (trainMouvementState[TRAINS] = {progressingtr}  $\Rightarrow$  trainState[TRAIN] = {progressing})
 $\wedge$  (trainMouvementState[TRAINS] = {movingtr}  $\Rightarrow$  trainState[TRAIN] = {moving}) )
EVENTS
UpdateSignalToGo ref_milestone ProgressTrain =
SELECT signalState = stop  $\wedge$  trainMouvementState(train)=stoppedtr  $\wedge$  trainState(tr)=stopped THEN
signalState := go END ;
MakeTrainProgress ref_milestone ProgressTrain =
SELECT signalState = go  $\wedge$  trainMouvementState(train)=stoppedtr THEN
trainMouvementState(train):=progressingtr || trainState(tr):=progressing END
END
    
```

EVENT-B FORMALIZATION OF THE GOAL PROGRESSTRAIN ALIGNMENT LINK

# Conclusion

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- A **model-based** approach to **align** complex systems **HLA models** with **SYSML/KAOS requirements models**:
  - **Graphical** to specify the alignment of a leaf goal with HLA elements responsible for its satisfaction,
  - **Formal** to verify the alignment links in Event-B.
- A set of transformation **rules** to **translate graphical alignment links** into **Event-B specifications**
- **Event-B specifications** are **formally analysed and proved** using **AtelierB**
- A **tool** has been **developed** using QVT

# Future work

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- Propagating the **impact** of updates on requirements models and/or HLA models on other models and on established alignment links.
- Integrating **security and safety** properties specification and traceability down to Event-B models (*new on-going PhD*)
- **Formal definition** of our metamodels and **verification** of the translation rules. This could be carried out by using EB4EB.

Thanks for your attention

Questions ???

